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Author(s):

S. Suantai, B. Panyanak and W. Phuengrattana

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A NEW ONE-STEP ITERATIVE PROCESS FOR APPROXIMATING COMMON FIXED POINTS OF A COUNTABLE FAMILY OF QUASI-NONEXPANSIVE MULTI-VALUED MAPPINGS IN CAT(0) SPACES

S. SUANTAI, B. PANYANAK AND W. PHUENGRATTANA*

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ABSTRACT. In this paper, we propose a new one-step iterative process for a countable family of quasi-nonexpansive multi-valued mappings in a CAT(0) space. We also prove strong and *Delta*-convergence theorems of the proposed iterative process under some control conditions. Our main results extend and generalize many results in the literature.

Keywords: Fixed point, quasi-nonexpansive multi-valued mappings, CAT(0) spaces.

MSC(2010): Primary: 47H09; Secondary: 47H10; 47J25.

1. Introduction

Let (X, d) be a metric space. A geodesic joining x to y (where $x, y \in X$) is a map γ from a closed interval $[0, l] \subset \mathbb{R}$ to X such that $\gamma(0) = x, \gamma(l) = y$ and $d(\gamma(t_1), \gamma(t_2)) = |t_1 - t_2|$ for all $t_1, t_2 \in [0, l]$. Thus γ is an isometry and d(x, y) = l. The image of γ is called a geodesic (or metric) segment joining x and y. When it is unique, this geodesic is denoted by [x, y]. We write $\alpha x \oplus (1 - \alpha)y$ for the unique point z in the geodesic segment joining from x to y such that $d(x, z) = (1 - \alpha)d(x, y)$ and $d(y, z) = \alpha d(x, y)$ for $\alpha \in [0, 1]$. The space Xis said to be a geodesic metric space if every two points of X are joined by a geodesic, and X is said to be uniquely geodesic if there is exactly one geodesic joining x and y for each $x, y \in X$. A subset D of X is said to be convex if Dincludes every geodesic segment joining any two of its points.

Following [3], a metric space X is said to be a CAT(0) space if it is geodesically connected and if every geodesic triangle in X is at least as thin as its comparison triangle in the Euclidean plane \mathbb{E}^2 . It is well known that any complete,

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^{*}Corresponding author.

simply connected Riemannian manifold having nonpositive sectional curvature is a CAT(0) space. Other examples include Pre-Hilbert spaces [3], R-trees [18], the complex Hilbert ball with a hyperbolic metric [15], and many others. It follows from [3] that CAT(0) spaces are uniquely geodesic metric spaces. The fixed point theory in CAT(0) spaces was first studied by Kirk [16, 17]. He showed that every nonexpansive (single-valued) mapping defined on a bounded closed convex subset of a complete CAT(0) space always has a fixed point. Since then, there have been many researches concerning the existence and the convergence of fixed points for single-valued and multi-valued mappings in such spaces (e.g., see [2, 5, 7, 8, 18-20]).

The study of fixed points for nonexpansive multi-valued mappings using the Pompeiu-Hausdorff metric was initiated by Markin [21]. Different iterative processes have been used to approximate fixed points of nonexpansive and quasi-nonexpansive multi-valued mappings; in particular, Sastry and Babu [24] considered Mann and Ishikawa iterative processes for a multi-valued mapping Twith a fixed point p and proved that these iterative processes converge to a fixed point q of T under certain conditions in Hilbert spaces. Moreover, they illustrated that fixed point q may be different from p. Later, in 2007, Panyanak [22] generalized the results of Sastry and Babu [24] to uniformly convex Banach spaces and proved a convergence theorem of Mann iterative processes for a mapping defined on a noncompact domain. Since then, the strong convergence of the Mann and Ishikawa iterative processes for multi-valued mappings has been rapidly developed, and many papers have appeared (e.g., see [6, 12, 25, 28]). Among other things, Shahzad and Zegeye [26] defined two types of Ishikawa iterative processes and proved strong convergence theorems for such iterative processes involving quasi-nonexpansive multi-valued mappings in uniformly convex Banach spaces. Recently, Abkar and Eslamian [1] established strong and *Delta*-convergence theorems for the multi-step iterative process for a finite family of quasi-nonexpansive multi-valued mappings in complete CAT(0)spaces.

In this paper, motivated by the above results, we propose a new one-step iterative process for a countable family of quasi-nonexpansive multi-valued mappings in CAT(0) spaces and prove strong and *Delta*-convergence theorems for the proposed iterative process in CAT(0) spaces. We finally provide an example to support our main result.

2. Preliminaries

For a nonempty set X, we let $\mathcal{P}(X)$ be the power set of X and $2^X = \mathcal{P}(X) - \{\emptyset\}$. For a metric space $(X, d), x \in X$, and $A, B \in 2^X$, let $B(x, \varepsilon) = \{y \in X : d(x, y) < \varepsilon\}$, dist $(x, B) = \inf\{d(x, y) : y \in B\}$, and $h(A, B) = \sup\{\text{dist}(x, B) : x \in A\}$.

We now recall some definitions of continuity for multi-valued mappings (see [4,14] for more details). Let (X, d) and (Y, d) be metric spaces. A multi-valued mapping $T: X \to 2^Y$ is said to be

- Hausdorff upper semi-continuous at x if for each $\varepsilon > 0$, there is $\delta > 0$ such that $h(Ty, Tx) < \varepsilon$ for each $y \in B(x, \delta)$;
- Hausdorff lower semi-continuous at x if for each $\varepsilon > 0$, there is $\delta > 0$ such that $h(Tx, Ty) < \varepsilon$ for each $y \in B(x, \delta)$;
- continuous at x if T is Hausdorff upper and lower semi-continuous at x.

We say that the multi-valued mapping T is continuous if it is continuous at each point in X.

Let D be a nonempty subset of a metric space X. Let CB(D) and KC(D) denote the families of nonempty closed bounded subsets and nonempty compact convex subsets of D, respectively. The *Pompeiu-Hausdorff distance* [23] on CB(D) is defined by

$$H(A,B) = \max\left\{\sup_{x \in A} \operatorname{dist}(x,B), \sup_{y \in B} \operatorname{dist}(y,A)\right\} \text{ for } A, B \in CB(D),$$

where $dist(x, D) = inf\{d(x, y) : y \in D\}$ is the distance from a point x to a subset D.

Note that a continuous multi-valued mapping behaves like a continuous single-valued mapping [14], that is, if a multi-valued mapping $T: D \to CB(D)$ is continuous then for every sequence $\{x_n\}$ in D such that $\lim_{n\to\infty} x_n = x$, we have $\lim_{n\to\infty} H(Tx_n, Tx) = 0$.

The set of fixed points of a multi-valued mapping $T: D \to CB(D)$ will be denoted by $F(T) = \{x \in D : x \in Tx\}.$

Definition 2.1. A multi-valued mapping $T: D \to CB(D)$ is said to be

- (i) nonexpansive [21] if $H(Tx, Ty) \leq d(x, y)$, for all $x, y \in D$,
- (ii) quasi-nonexpansive [24] if $F(T) \neq \emptyset$ and $H(Tx, Tp) \leq d(x, p)$, for all $x \in D$ and $p \in F(T)$,
- (iii) hemicompact if for any sequence $\{x_n\}$ in D such that $\lim_{n\to\infty} \operatorname{dist}(x_n, Tx_n) = 0$ there exists a subsequence $\{x_{n_i}\}$ of $\{x_n\}$ such that $\lim_{i\to\infty} x_{n_i} = p \in D$.

Definition 2.2. A multi-valued mapping $T: D \to CB(D)$ is said to satisfy *condition* (E_{μ}) provided that

$$\operatorname{dist}(x, Ty) \le \mu \operatorname{dist}(x, Tx) + d(x, y)$$

for each $x, y \in D$. We say that T satisfies *condition* (E) whenever T satisfies (E_{μ}) for some $\mu \geq 1$.

Remark 2.3. From the above definitions, it is clear that:

(i) if T is nonexpansive, then T satisfies the condition (E_1) ;

(ii) if D is compact, then T is hemicompact.

Although the condition (E) implies the quasi-nonexpansiveness for singlevalued mappings [13], but it is not true for multi-valued mappings as the following example.

Example 2.4 ([27, Example 1]). Let $D = [0, \infty)$ and $T : D \to CB(D)$ be defined by

$$Tx = [x, 2x]$$
 for all $x \in D$.

Then T satisfies condition (E) and is not quasi-nonexpansive.

Notice also that the classes of (multi-valued) quasi-nonexpansive mappings, continuous mappings and mappings satisfying condition (E) are different (see Examples 2.5-2.7).

Example 2.5 ([13, Example 2]). Let D = [-1, 1] and $T : D \to CB(D)$ be defined by

$$Tx = \begin{cases} \left\{ \frac{x}{1+|x|} \sin(\frac{1}{x}) \right\} & \text{if } x \neq 0; \\ \{0\} & \text{if } x = 0. \end{cases}$$

Then T is quasi-nonexpansive and does not satisfy condition (E).

Example 2.6 ([5, p. 984]). Let D = [0, 1] and $T : D \to CB(D)$ be defined by

$$Tx = \begin{cases} \{x^2\} & \text{if } 0 \le x < 1; \\ \{0\} & \text{if } x = 1. \end{cases}$$

Then T is quasi-nonexpansive and is not continuous. Notice also that the mapping $Tx = \{x^2\}$ on [0, 1] is continuous but is not quasi-nonexpansive nor satisfies condition (E).

Example 2.7 ([13, Example 3]). Let D = [-2, 1] and $T : D \to CB(D)$ be defined by

$$Tx = \begin{cases} \left\{ \frac{|x|}{2} \right\} & \text{if } -2 \le x < 1; \\ \left\{ -\frac{1}{2} \right\} & \text{if } x = 1. \end{cases}$$

Then T satisfies condition (E) and is not continuous.

The notion of the asymptotic center can be introduced in the general setting of a CAT(0) space X as follows: Let $\{x_n\}$ be a bounded sequence in X. For $x \in X$, we define a mapping $r(\cdot, \{x_n\}) : X \to [0, \infty)$ by

$$r(x, \{x_n\}) = \limsup_{n \to \infty} d(x, x_n).$$

The asymptotic radius of $\{x_n\}$ is given by

$$r(\{x_n\}) = \inf \{r(x, \{x_n\}) : x \in X\},\$$

and the asymptotic center of $\{x_n\}$ is the set

$$A(\{x_n\}) = \{x \in X : r(x, \{x_n\}) = r(\{x_n\})\}$$

It is known by [10] that in a CAT(0) space, the asymptotic center $A(\{x_n\})$ consists of exactly one point.

We now give the definition and collect some basic properties of the Δ -convergence which will be used in the sequel.

Definition 2.8 ([19]). A sequence $\{x_n\}$ in a CAT(0) space X is said to Δ converge to $x \in X$ if x is the unique asymptotic center of $\{u_n\}$ for every subsequence $\{u_n\}$ of $\{x_n\}$. In this case, we write Δ -lim_{$n\to\infty$} $x_n = x$ and call x the Δ -limit of $\{x_n\}$.

Lemma 2.9 ([19]). Every bounded sequence in a CAT(0) space has a Δ -convergent subsequence.

Lemma 2.10 ([9]). If D is a nonempty closed convex subset of a CAT(0) space X and if $\{x_n\}$ is a bounded sequence in D, then the asymptotic center of $\{x_n\}$ is in D.

Lemma 2.11 ([11]). Let $\{x_n\}$ be a sequence in a CAT(0) space X with $A(\{x_n\}) = \{x\}$. If $\{u_n\}$ is a subsequence of $\{x_n\}$ with $A(\{u_n\}) = \{u\}$ and $\{d(x_n, u)\}$ converges, then x = u.

Lemma 2.12 ([3]). Let X be a geodesic metric space. The following are equivalent:

- (i) X is a CAT(0) space.
- (ii) X satisfies the (CN) inequality: If $x, y \in X$ and $\frac{x \oplus y}{2}$ is the midpoint of x and y, then

$$d\left(z, \frac{x \oplus y}{2}\right)^2 \le \frac{1}{2}d(z, x)^2 + \frac{1}{2}d(z, y)^2 - \frac{1}{4}d(x, y)^2, \text{ for all } z \in X.$$

The following lemma is a generalization of the (CN) inequality which can be found in [11].

Lemma 2.13. Let X be a CAT(0) space. Then

$$d(z,\lambda x \oplus (1-\lambda)y)^2 \le \lambda d(z,x)^2 + (1-\lambda)d(z,y)^2 - \lambda(1-\lambda)d(x,y)^2,$$

for any $\lambda \in [0,1]$ and $x, y, z \in X$.

In 2012, Dhompongsa et al. [8] introduced the following notation in CAT(0) spaces: Let x_1, \ldots, x_n be points in a CAT(0) space X and $\lambda_1, \ldots, \lambda_n \in (0, 1)$ with $\sum_{i=1}^n \lambda_i = 1$, we write (2.1)

$$\bigoplus_{i=1}^{n} \lambda_{i} x_{i} := (1-\lambda_{n}) \left(\frac{\lambda_{1}}{1-\lambda_{n}} x_{1} \oplus \frac{\lambda_{2}}{1-\lambda_{n}} x_{2} \oplus \dots \oplus \frac{\lambda_{n-1}}{1-\lambda_{n}} x_{n-1} \right) \oplus \lambda_{n} x_{n}.$$

The definition of \bigoplus is an ordered one in the sense that it depends on the order of points x_1, \ldots, x_n . Under (2.1) we obtain that

$$d\left(\bigoplus_{i=1}^{n} \lambda_i x_i, y\right) \le \sum_{i=1}^{n} \lambda_i d(x_i, y) \text{ for each } y \in X.$$

3. Main results

In this section, we first introduce a new one-step iterative process for a countable family of quasi-nonexpansive multi-valued mappings in CAT(0) spaces. Let D be a nonempty closed convex subset of a CAT(0) space X and let $\{T_i\}$ be a countable family of quasi-nonexpansive multi-valued mappings of D into CB(D) with $\bigcap_{i=1}^{\infty} F(T_i) \neq \emptyset$ and $T_i p = \{p\}$ for all $i \in \mathbb{N}$ and $p \in \bigcap_{i=1}^{\infty} F(T_i)$. For $x_1 \in D$, the sequence $\{x_n\}$ generated by

(3.1)
$$x_{n+1} = \bigoplus_{i=0}^{n} \lambda_n^{(i)} y_n^{(i)}, \text{ for all } n \in \mathbb{N},$$

where $y_n^{(0)} = x_n$, $y_n^{(i)} \in T_i x_n$ and the sequences $\{\lambda_n^{(i)}\} \subset (0,1)$ satisfying $\sum_{i=0}^n \lambda_n^{(i)} = 1$.

Note that, if we put

$$W_n^{(m)} = \bigoplus_{i=0}^m \delta_n^{(i,m)} y_n^{(i)},$$

where
$$\delta_n^{(i,m)} = \frac{\lambda_n^{(i)}}{\sum_{j=0}^m \lambda_n^{(j)}}$$
 for $i = 0, 1, ..., m$, then we get
 $W_n^{(m)}$
 $= \left(1 - \delta_n^{(m,m)}\right) \left(\frac{\delta_n^{(0,m)}}{1 - \delta_n^{(m,m)}} x_n \oplus \frac{\delta_n^{(1,m)}}{1 - \delta_n^{(m,m)}} y_n^{(1)} \oplus \dots \oplus \frac{\delta_n^{(m-1,m)}}{1 - \delta_n^{(m,m)}} y_n^{(m-1)}\right)$
 $\oplus \delta_n^{(m,m)} y_n^{(m)}$
 $= \left(1 - \delta_n^{(m,m)}\right) \left(\delta_n^{(0,m-1)} x_n \oplus \delta_n^{(1,m-1)} y_n^{(1)} \oplus \dots \oplus \delta_n^{(m-1,m-1)} y_n^{(m-1)}\right) \oplus \delta_n^{(m,m)} y_n^{(m)}$
 $= \left(1 - \delta_n^{(m,m)}\right) \left(\frac{\lambda_n^{(0)}}{\sum\limits_{j=0}^{m-1} \lambda_n^{(j)}} x_n \oplus \frac{\lambda_n^{(1)}}{\sum\limits_{j=0}^{m-1} \lambda_n^{(j)}} y_n^{(1)} \oplus \dots \oplus \frac{\lambda_n^{(m-1)}}{\sum\limits_{j=0}^{m-1} \lambda_n^{(j)}} y_n^{(m-1)}\right) \oplus \delta_n^{(m,m)} y_n^{(m)}$
 $= \left(1 - \delta_n^{(m,m)}\right) W_n^{(m-1)} \oplus \delta_n^{(m,m)} y_n^{(m)}$
 $= \frac{\sum\limits_{j=0}^{m-1} \lambda_n^{(j)}}{\sum\limits_{j=0}^{m} \lambda_n^{(j)}} W_n^{(m-1)} \oplus \frac{\lambda_n^{(m)}}{\sum\limits_{j=0}^{m} \lambda_n^{(j)}} y_n^{(m)}.$

Therefore, the following result holds:

(3.2)
$$W_n^{(m)} = \frac{\sum_{j=0}^{m-1} \lambda_n^{(j)}}{\sum_{j=0}^m \lambda_n^{(j)}} W_n^{(m-1)} \oplus \frac{\lambda_n^{(m)}}{\sum_{j=0}^m \lambda_n^{(j)}} y_n^{(m)}.$$

The following two lemmas are useful and crucial for our main theorems.

Lemma 3.1. Let D be a nonempty closed convex subset of a complete CAT(0)space X and let $\{T_i\}$ be a countable family of quasi-nonexpansive multi-valued mappings of D into CB(D) with $\bigcap_{i=1}^{\infty} F(T_i) \neq \emptyset$ and $T_ip = \{p\}$ for all $i \in \mathbb{N}$ and $p \in \bigcap_{i=1}^{\infty} F(T_i)$. For $x_1 \in D$, consider the sequence $\{x_n\}$ generated by (3.1). Then, $\lim_{n\to\infty} d(x_n, p)$ exists for all $p \in \bigcap_{i=1}^{\infty} F(T_i)$.

Proof. For $p \in \bigcap_{i=1}^{\infty} F(T_i)$, we have by (3.1) that

$$d(x_{n+1}, p) = d\left(\bigoplus_{i=0}^{n} \lambda_n^{(i)} y_n^{(i)}, p\right)$$

$$\leq \sum_{i=0}^{n} \lambda_n^{(i)} d(y_n^{(i)}, p)$$

$$= \sum_{i=0}^{n} \lambda_n^{(i)} \operatorname{dist}(y_n^{(i)}, T_i p)$$

$$\leq \sum_{i=0}^{n} \lambda_n^{(i)} H(T_i x_n, T_i p)$$

$$\leq \sum_{i=0}^{n} \lambda_n^{(i)} d(x_n, p)$$

$$= d(x_n, p).$$

This implies that $\lim_{n\to\infty} d(x_n, p)$ exists for all $p \in \bigcap_{i=1}^{\infty} F(T_i)$.

Lemma 3.2. Let D be a nonempty closed convex subset of a complete CAT(0)space X and let $\{T_i\}$ be a countable family of quasi-nonexpansive multi-valued mappings of D into CB(D) with $\bigcap_{i=1}^{\infty} F(T_i) \neq \emptyset$ and $T_ip = \{p\}$ for all $i \in \mathbb{N}$ and $p \in \bigcap_{i=1}^{\infty} F(T_i)$. For $x_1 \in D$, consider the sequence $\{x_n\}$ generated by (3.1). If $\lim_{n\to\infty} \lambda_n^{(i)}$ exists for all $i \in \mathbb{N} \cup \{0\}$ and lies in (0,1), then $\lim_{n\to\infty} dist(x_n, T_ix_n) = 0$ for all $i \in \mathbb{N}$. *Proof.* For each $p \in \bigcap_{i=1}^{\infty} F(T_i)$, we obtain by (3.1) that

$$d(x_{n+1},p) = d\left(\bigoplus_{i=0}^n \lambda_n^{(i)} y_n^{(i)}, p\right) = d\left(\bigoplus_{i=0}^n \frac{\lambda_n^{(i)}}{\sum\limits_{j=0}^n \lambda_n^{(j)}} y_n^{(i)}, p\right) = d(W_n^{(n)}, p).$$

It follows by Lemma 2.13 and (3.2) that

$$\begin{aligned} d(x_{n+1},p)^2 &= d\left(\sum_{\substack{j=0\\j=0}}^{n-1}\lambda_n^{(j)}} W_n^{(n-1)} \oplus \frac{\lambda_n^{(n)}}{\sum_{j=0}^n \lambda_n^{(j)}} y_n^{(n)}, p\right)^2 \\ &\leq \frac{\sum_{j=0}^{n-1}\lambda_n^{(j)}}{\sum_{j=0}^n \lambda_n^{(j)}} d(W_n^{(n-1)},p)^2 + \frac{\lambda_n^{(n)}}{\sum_{j=0}^n \lambda_n^{(j)}} d(y_n^{(n)},p)^2 \\ &\quad - \frac{\lambda_n^{(n)}}{\sum_{j=0}^n \lambda_n^{(j)}} \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-1)},y_n^{(n)})^2 \\ &= \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-1)},p)^2 + \lambda_n^{(n)} d(y_n^{(n)},p)^2 - \lambda_n^{(n)} \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-1)},y_n^{(n)})^2 \\ &= \sum_{j=0}^{n-1}\lambda_n^{(j)} d\left(\sum_{j=0}^{n-2}\lambda_n^{(j)} W_n^{(n-2)} \oplus \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1}\lambda_n^{(j)}} y_n^{(n-1)},p\right)^2 + \lambda_n^{(n)} d(y_n^{(n)},p)^2 \\ &\quad -\lambda_n^{(n)} \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-1)},y_n^{(n)})^2 \\ &\leq \sum_{j=0}^{n-1}\lambda_n^{(j)} d\left(\sum_{j=0}^{n-2}\lambda_n^{(j)} d(W_n^{(n-2)},p)^2 + \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1}\lambda_n^{(j)}} d(y_n^{(n-1)},p)^2\right) \\ &= \sum_{j=0}^{n-1}\lambda_n^{(j)} d\left(\sum_{j=0}^{n-2}\lambda_n^{(j)} W_n^{(n-2)} \oplus \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1}\lambda_n^{(j)}} y_n^{(n-1)},p\right)^2 + \lambda_n^{(n)} d(y_n^{(n)},p)^2 \\ &-\lambda_n^{(n)} \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-2)},y_n^{(n)})^2 \\ &= \sum_{j=0}^{n-1}\lambda_n^{(j)} d\left(\sum_{j=0}^{n-2}\lambda_n^{(j)} W_n^{(n-2)} \oplus \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1}\lambda_n^{(j)}} y_n^{(n-1)},p\right)^2 + \lambda_n^{(n)} d(y_n^{(n)},p)^2 \\ &-\lambda_n^{(n)} \sum_{j=0}^{n-1}\lambda_n^{(j)} d(W_n^{(n-1)},y_n^{(n)})^2 \end{aligned}$$

$$\leq \sum_{j=0}^{n-1} \lambda_n^{(j)} \left(\sum_{j=0}^{n-2} \lambda_n^{(j)} d(W_n^{(n-2)}, p)^2 + \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1} \lambda_n^{(j)}} d(y_n^{(n-1)}, p)^2 \right) \\ - \frac{\sum_{j=0}^{n-2} \lambda_n^{(j)}}{\sum_{j=0}^{n-1} \lambda_n^{(j)}} \frac{\lambda_n^{(n-1)}}{\sum_{j=0}^{n-1} \lambda_n^{(j)}} d(W_n^{(n-2)}, y_n^{(n-1)})^2 \right) + \lambda_n^{(n)} d(y_n^{(n)}, p)^2 \\ - \lambda_n^{(n)} \sum_{j=0}^{n-1} \lambda_n^{(j)} d(W_n^{(n-1)}, y_n^{(n)})^2 \\ = \sum_{j=0}^{n-2} \lambda_n^{(j)} d(W_n^{(n-2)}, p)^2 + \lambda_n^{(n-1)} d(y_n^{(n-1)}, p)^2 + \lambda_n^{(n)} d(y_n^{(n)}, p)^2 \\ - \frac{\lambda_n^{(n-1)} \sum_{j=0}^{n-2} \lambda_n^{(j)}}{\sum_{j=0}^{n-1} \lambda_n^{(j)}} d(W_n^{(n-2)}, y_n^{(n-1)})^2 - \lambda_n^{(n)} \sum_{j=0}^{n-1} \lambda_n^{(j)} d(W_n^{(n-1)}, y_n^{(n)})^2 \\ \leq \sum_{j=0}^{n-3} \lambda_n^{(j)} d(W_n^{(n-3)}, p)^2 + \lambda_n^{(n-2)} d(y_n^{(n-2)}, p)^2 + \lambda_n^{(n-1)} d(y_n^{(n-1)}, p)^2 \\ + \lambda_n^{(n)} d(y_n^{(n)}, p)^2 - \frac{\lambda_n^{(n-2)} \sum_{j=0}^{n-3} \lambda_n^{(j)}}{\sum_{j=0}^{n-2} \lambda_n^{(j)}} d(W_n^{(n-3)}, y_n^{(n-2)})^2 \\ - \frac{\lambda_n^{(n-1)} \sum_{j=0}^{n-2} \lambda_n^{(j)}}{\sum_{j=0}^{n-1} \lambda_n^{(j)}} d(W_n^{(n-2)}, y_n^{(n-1)})^2 - \lambda_n^{(N)} \sum_{j=0}^{n-1} \lambda_n^{(j)} d(W_n^{(n-1)}, y_n^{(n)})^2 \\ \leq \lambda_n^{(0)} d(W_n^{(0)}, p)^2 + \sum_{k=1}^{n} \lambda_n^{(k)} d(y_n^{(k)}, p)^2 - \sum_{k=1}^{n} \frac{\lambda_n^{(k)} \sum_{j=0}^{k-1} \lambda_n^{(j)}}{\sum_{j=0}^k \lambda_n^{(j)}} d(W_n^{(k-1)}, y_n^{(k)})^2 \\ \leq \sum_{k=0}^{n} \lambda_n^{(k)} d(x_n, p)^2 - \sum_{k=1}^{n} \frac{\lambda_n^{(k)} \sum_{j=0}^{k-1} \lambda_n^{(j)}}{\sum_{j=0}^k \lambda_n^{(j)}} d(W_n^{(k-1)}, y_n^{(k)})^2 \\ \leq \sum_{k=0}^{n} \lambda_n^{(k)} d(x_n, p)^2 - \sum_{k=1}^{n} \frac{\lambda_n^{(k)} \sum_{j=0}^{k-1} \lambda_n^{(j)}}{\sum_{j=0}^k \lambda_n^{(j)}} d(W_n^{(k-1)}, y_n^{(k)})^2.$$

This implies that

(3.3)
$$\sum_{k=1}^{n} \frac{\lambda_n^{(k)} \sum_{j=0}^{k-1} \lambda_n^{(j)}}{\sum_{j=0}^{k} \lambda_n^{(j)}} d(W_n^{(k-1)}, y_n^{(k)})^2 \le d(x_n, p)^2 - d(x_{n+1}, p)^2$$

Since $0 < \lambda_n^{(0)} \leq \sum_{j=0}^k \lambda_n^{(j)} \leq 1$ for all k = 1, 2, ..., n, we have $0 < \lambda_n^{(0)} \lambda_n^{(k)} \leq \lambda_n^{(k)} \sum_{j=0}^k \lambda_n^{(j)}$. So, $0 < \lambda_n^{(0)} \lambda_n^{(k)} \leq \frac{\lambda_n^{(k)} \sum_{j=0}^{k-1} \lambda_n^{(j)}}{\sum_{j=0}^k \lambda_n^{(j)}}$ for all k = 1, 2, ..., n. Then (3.3) becomes

(3.4)
$$\sum_{k=1}^{n} \lambda_n^{(0)} \lambda_n^{(k)} d(W_n^{(k-1)}, y_n^{(k)})^2 \le d(x_n, p)^2 - d(x_{n+1}, p)^2.$$

By Lemma 3.1 and the condition $\lim_{n\to\infty} \lambda_n^{(i)}$ exists for all $i \in \mathbb{N} \cup \{0\}$ and lies in (0, 1), we get that

(3.5)
$$\lim_{n \to \infty} d(x_n, y_n^{(1)}) = 0$$
 and $\lim_{n \to \infty} d(W_n^{(k-1)}, y_n^{(k)}) = 0$ for all $k \ge 2$.

Then, for $k \geq 2$, we have

$$\begin{split} d(x_n, y_n^{(k)}) &\leq d(x_n, W_n^{(k-1)}) + d(W_n^{(k-1)}, y_n^{(k)}) \\ &= d\left(x_n, \bigoplus_{i=0}^{k-1} \frac{\lambda_n^{(i)}}{\sum\limits_{j=0}^{k-1} \lambda_n^{(j)}} y_n^{(i)}\right) + d(W_n^{(k-1)}, y_n^{(k)}) \\ &\leq \sum_{i=0}^{k-1} \frac{\lambda_n^{(i)}}{\sum\limits_{j=0}^{k-1} \lambda_n^{(j)}} d(x_n, y_n^{(i)}) + d(W_n^{(k-1)}, y_n^{(k)}) \\ &= \sum_{i=1}^{k-1} \frac{\lambda_n^{(i)}}{\sum\limits_{j=0}^{k-1} \lambda_n^{(j)}} d(x_n, y_n^{(i)}) + d(W_n^{(k-1)}, y_n^{(k)}). \end{split}$$

This implies by (3.5) that $\lim_{n\to\infty} d(x_n, y_n^{(k)}) = 0$ for all $k \ge 1$. Since $\operatorname{dist}(x_n, T_i x_n) \le d(x_n, y_n^{(i)})$ for all $i \in \mathbb{N}$, it follows that $\lim_{n\to\infty} \operatorname{dist}(x_n, T_i x_n) = 0$ for all $i \in \mathbb{N}$.

In what follows we get a Δ -convergence theorem for a countable family of quasi-nonexpansive multi-valued mappings in complete CAT(0) spaces.

Theorem 3.3. Let D be a nonempty closed convex subset of a complete CAT(0) space X and let $\{T_i\}$ be a countable family of quasi-nonexpansive multi-valued

mappings of D into KC(D) satisfying the condition (E). Assume that $\bigcap_{i=1}^{\infty} F(T_i) \neq \emptyset$ and $T_i p = \{p\}$ for all $i \in \mathbb{N}$ and $p \in \bigcap_{i=1}^{\infty} F(T_i)$. Suppose that $\lim_{n\to\infty} \lambda_n^{(i)}$ exists for all $i \in \mathbb{N} \cup \{0\}$ and lies in (0,1). Then, the sequence $\{x_n\}$ generated by (3.1) Δ -converges to a common fixed point of $\{T_i\}$.

Proof. By Lemmas 3.1 and 3.2, we have $\lim_{n\to\infty} d(x_n, p)$ exists for all $p \in \bigcap_{i=1}^{\infty} F(T_i)$ and $\lim_{n\to\infty} \operatorname{dist}(x_n, T_i x_n) = 0$ for all $i \in \mathbb{N}$. Thus the sequence $\{x_n\}$ is bounded. We put $\omega_{\Delta}(x_n) := \bigcup A(\{u_n\})$, where the union is taken over all subsequences $\{u_n\}$ of $\{x_n\}$. Let $u \in \omega_{\Delta}(x_n)$. Then, there exists a subsequence $\{u_n\}$ of $\{x_n\}$ such that $A(\{u_n\}) = \{u\}$. By Lemma 2.9, there exists a subsequence $\{u_{n_j}\}$ of $\{u_n\}$ such that $\Delta\operatorname{-lim}_{j\to\infty} u_{n_j} = z \in D$. We will show that $z \in T_1 z$. Since $T_1 z$ is compact, for all $j \in \mathbb{N}$, we can choose $y_{n_j} \in T_1 z$ such that $d(u_{n_j}, y_{n_j}) = \operatorname{dist}(u_{n_j}, T_1 z)$ and $\{y_{n_j}\}$ has a convergent subsequence $\{y_{n_k}\}$ with $\lim_{k\to\infty} y_{n_k} = q \in T_1 z$. By condition (E), we have

$$\operatorname{dist}(u_{n_k}, T_1 z) \le \mu \operatorname{dist}(u_{n_k}, T_1 u_{n_k}) + d(u_{n_k}, z).$$

Then we have

$$d(u_{n_k}, q) \le d(u_{n_k}, y_{n_k}) + d(y_{n_k}, q)$$

= dist $(u_{n_k}, T_1 z) + d(y_{n_k}, q)$
 $\le \mu \text{dist}(u_{n_k}, T_1 u_{n_k}) + d(u_{n_k}, z) + d(y_{n_k}, q).$

This implies that

$$\limsup_{k \to \infty} d(u_{n_k}, q) \le \limsup_{k \to \infty} d(u_{n_k}, z).$$

By the uniqueness of asymptotic centers, we have $z = q \in T_1 z$. Similarly, it can be shown that $z \in T_i z$ for all i = 2, ..., N. Then, $z \in \bigcap_{i=1}^{\infty} F(T_i)$ and so $\lim_{n\to\infty} d(x_n, z)$ exists. Suppose that $u \neq z$. By the uniqueness of asymptotic centers, we have

$$\begin{split} \limsup_{j \to \infty} d(u_{n_j}, z) &< \limsup_{j \to \infty} d(u_{n_j}, u) \\ &\leq \limsup_{n \to \infty} d(u_n, u) \\ &< \limsup_{n \to \infty} d(u_n, z) \\ &= \limsup_{n \to \infty} d(u_n, z) \\ &= \limsup_{j \to \infty} d(u_{n_j}, z). \end{split}$$

This is a contradiction, hence $u = z \in \bigcap_{i=1}^{\infty} F(T_i)$. This shows that $\omega_{\Delta}(x_n) \subset \bigcap_{i=1}^{\infty} F(T_i)$.

Next, we show that $\omega_{\Delta}(x_n)$ consists of exactly one point. Let $\{u_n\}$ be a subsequence of $\{x_n\}$ with $A(\{u_n\}) = \{p\}$ and let $A(\{x_n\}) = \{q\}$. Since $p \in \omega_{\Delta}(x_n) \subset \bigcap_{i=1}^{\infty} F(T_i)$, it follows that $\lim_{n\to\infty} d(x_n, p)$ exists. By Lemma

2.11, we obtain that p = q. Hence, the sequence $\{x_n\} \Delta$ -converges to a common fixed point of $\{T_i\}$.

The following result is a strong convergence theorem for a countable family of quasi-nonexpansive multi-valued mappings in complete CAT(0) spaces.

Theorem 3.4. Let D be a nonempty closed convex subset of a complete CAT(0)space X and let $\{T_i\}$ be a countable family of continuous and quasi-nonexpansive multi-valued mappings of D into CB(D) with $\bigcap_{i=1}^{\infty} F(T_i) \neq \emptyset$ and $T_i p = \{p\}$ for all $i \in \mathbb{N}$ and $p \in \bigcap_{i=1}^{\infty} F(T_i)$. Let the sequence $\{x_n\}$ generated by (3.1) with $\lim_{n\to\infty} \lambda_n^{(i)}$ exist for all $i \in \mathbb{N} \cup \{0\}$ and lie in (0,1). Assume that one member of the family $\{T_i\}$ is hemicompact. Then, $\{x_n\}$ converges strongly to a common fixed point of $\{T_i\}$.

Proof. By Lemma 3.2, $\lim_{n\to\infty} \operatorname{dist}(x_n, T_i x_n)$ for all $i \in \mathbb{N}$. Without loss of generality, we assume that T_1 is hemicompact. Then there exists a subsequence $\{x_{n_j}\}$ of $\{x_n\}$ such that $\lim_{j\to\infty} x_{n_j} = p \in D$. By continuity of T_i , we have $\lim_{j\to\infty} \operatorname{dist}(x_{n_j}, T_i x_{n_j}) = \operatorname{dist}(p, T_i p)$ for all $i \in \mathbb{N}$. This implies that $\operatorname{dist}(p, T_i p) = 0$ for all $i \in \mathbb{N}$ and hence $p \in \bigcap_{i=1}^{\infty} F(T_i)$. It follows by Lemma 3.1 that $\{x_n\}$ converges strongly to p.

Remark 3.5. Since any $CAT(\kappa)$ space is a $CAT(\kappa')$ space for $\kappa' \ge \kappa$ (see [3]), all our results immediately apply to any $CAT(\kappa)$ space with $\kappa \le 0$.

Finally, we give a numerical example supporting Theorems 3.3 and 3.4.

Example 3.6. Let X be a real line with the Euclidean norm and D = [0, 1]. For $x \in D$, i = 1, 2, ..., we define mappings T_i on D as follows:

$$T_i x = \left[0, \frac{x}{i}\right] \text{ for all } i \in \mathbb{N}.$$

Let the sequence $\{x_n\}$ be generated by

(3.6)
$$x_{n+1} = \bigoplus_{i=0}^{n} \lambda_n^{(i)} y_n^{(i)}, \text{ for all } n \in \mathbb{N},$$

where $y_n^{(0)} = x_n, y_n^{(i)} \in T_i x_n$ and the sequences $\{\lambda_n^{(i)}\}$ defined by

$$\lambda_n^{(i)} = \begin{cases} \frac{1}{2^{i+1}} \left(\frac{n}{n+1} \right), & n \ge i+1 \\ 1 - \frac{n}{n+1} \left(\sum_{k=1}^n \frac{1}{2^k} \right), & n = i \\ 0, & n < i. \end{cases}$$

Obviously, T_i is quasi-nonexpansive and satisfies condition (E) for all $i \in \mathbb{N}$ and $T_i(0) = \{0\}$ such that $\bigcap_{i=1}^{\infty} F(T_i) = \{0\}$. It can be observed that all the assumptions of Theorems 3.3 and 3.4 are satisfied.

For any arbitrary $x_1 \in D = [0, 1]$, we put $y_n^{(i)} = \frac{x_n}{5i}$ for all $i \in \mathbb{N}$. Then, we rewrite the algorithm (3.6) as follows:

$$x_{n+1} = \lambda_n^{(0)} x_n + \frac{\lambda_n^{(1)} x_n}{5} + \frac{\lambda_n^{(2)} x_n}{10} + \dots + \frac{\lambda_n^{(n)} x_n}{5n}, \text{ for all } n \in \mathbb{N},$$

where

$$\left(\lambda_{n}^{(i)}\right) = \begin{pmatrix} \frac{1}{4} & \frac{3}{4} & 0 & 0 & 0 & 0 & \cdots & 0 & \cdots \\ \frac{1}{3} & \frac{1}{6} & \frac{1}{2} & 0 & 0 & 0 & \cdots & 0 & \cdots \\ \frac{3}{8} & \frac{3}{16} & \frac{3}{32} & \frac{11}{32} & 0 & 0 & \cdots & 0 & \cdots \\ \frac{2}{5} & \frac{1}{5} & \frac{1}{10} & \frac{1}{20} & \frac{1}{4} & 0 & \cdots & 0 & \cdots \\ \vdots & \vdots \\ \frac{n}{2(n+1)} & \frac{n}{4(n+1)} & \frac{n}{8(n+1)} & \frac{n}{16(n+1)} & \frac{n}{32(n+1)} & \frac{n}{64(n+1)} & \cdots & \frac{n}{2^{i}(n+1)} & \cdots \\ \vdots & \ddots & \vdots & \ddots & \end{pmatrix}$$

The values of the sequence $\{x_n\}$ with different n are reported in Table 1.

TABLE 1. The values of the sequence $\{x_n\}$ in Example 3.6.

	$x_1 = 0.11$	$x_1 = 0.95$
n	x_n	x_n
1	0.1100000	0.9500000
2	0.0440000	0.3800000
3	0.0183333	0.1583333
4	0.0081545	0.0704253
5	0.0037986	0.0328065
6	0.0018280	0.0157875
7	0.0009008	0.0077801
8	0.0004520	0.0039036
9	0.0002300	0.0019863
10	0.0001184	0.0010222
÷	:	•
17	0.0000014	0.0000118
18	0.0000007	0.0000064
19	0.0000004	0.0000034
20	0.0000002	0.0000019

From Table 1, it is clear that $\{x_n\}$ converges to 0, where $\{0\} = \bigcap_{i=1}^{\infty} F(T_i)$.

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(Suthep Suantai) DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, CHIANG MAI UNIVERSITY, CHIANG MAI 50200, THAILAND.

E-mail address: suthep.s@cmu.ac.th

(Bancha Panyanak) DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, CHIANG MAI UNIVERSITY, CHIANG MAI 50200, THAILAND.

E-mail address: bancha.p@cmu.ac.th

(Withun Phuengrattana) DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE AND TECH-NOLOGY, NAKHON PATHOM RAJABHAT UNIVERSITY, NAKHON PATHOM 73000, THAILAND, AND RESEARCH CENTER FOR PURE AND APPLIED MATHEMATICS, RESEARCH AND DEVELOPMENT INSTITUTE, NAKHON PATHOM RAJABHAT UNIVERSITY, NAKHON PATHOM 73000, THAILAND.

E-mail address: withun_ph@yahoo.com