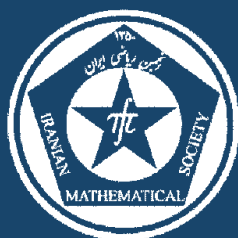


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On a Picone's identity for the $\mathcal{A}_{p(x)}$ -Laplacian and its applications

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ON A PICONE'S IDENTITY FOR THE $\mathcal{A}_{p(x)}$ -LAPLACIAN AND ITS APPLICATIONS

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ABSTRACT. We present a Picone's identity for the $\mathcal{A}_{p(x)}$ -Laplacian, which is an extension of the classic identity for the ordinary Laplace. Also, some applications of our results in Sobolev spaces with variable exponent are suggested.

Keywords: Picone's identity, $\mathcal{A}_{p(x)}$ -Laplacian, nonlinear elliptic problems.

MSC(2010): Primary: 35J66; Secondary: 35J92, 35B05, 11Y50.

1. Introduction and preliminaries

Since the pioneering work of M. Picone [15], efforts have been made to establish Picone identities for differential equations of various type (see [7, 13, 19]). Picone identities play an important role in the oscillation theory for ordinary or partial differential equations or systems. Let us recall the classical Picone's identity:

For differentiable functions $v > 0$ and $u \geq 0$, we have

$$(1.1) \quad |\nabla u|^2 + \frac{u^2}{v^2} |\nabla v|^2 - 2 \frac{u}{v} \nabla u \nabla v = |\nabla u|^2 - \nabla \left(\frac{u^2}{v} \right) \nabla v \geq 0.$$

Later Allegreto-Huang [1] presented a Picone's identity for the p -Laplacian, which is an extension of (1.1). As an immediate consequence, they obtained a wide array of applications including the simplicity of the eigenvalues, Sturmian comparison principles, oscillation theorems and Hardy inequalities to name a few.

Recently in [18] the author established a generalization to Picone's identity in the nonlinear framework. They showed, as an application of their results, that the Morse index of the zero solution to a semilinear elliptic boundary value

problem is 0 and also established a linear relationship between the components of the solution of a nonlinear elliptic system.

They proved that for differentiable functions $v > 0$ and $u \geq 0$ we have

$$(1.2) \quad |\nabla u|^2 + \frac{|\nabla u|^2}{f'(v)} + \left(\frac{u\sqrt{f'(v)}\nabla v}{f(v)} - \frac{\nabla u}{\sqrt{f'(v)}} \right)^2 = |\nabla u|^2 - \nabla\left(\frac{u^2}{f(v)}\right) \cdot \nabla v \geq 0$$

where $f(y) \neq 0$ and $f'(y) \geq 1$ for all $y \neq 0$; $f(0) = 0$.

Moreover, $|\nabla u|^2 - \nabla(u^2/f(v)) \cdot \nabla v = 0$ holds if and only if $u = cv$ for an arbitrary constant c . In a recent paper [3] Bal generalized the main result of [18] for the p -Laplacian operator. The aim of this paper is to prove a generalized analogue of Picone's identity for the $\mathcal{A}_{p(x)}$ -Laplacian and, using this, we deal with the problems of the type

$$(1.3) \quad \begin{cases} -\mathcal{A}_{p(x)}u = m(x)|u|^{p(x)-2}u, & x \in \Omega, \\ u = 0, & x \in \partial\Omega, \end{cases}$$

where $p \in C(\bar{\Omega})$ such that $2 \leq p(x) < \infty$, Ω is a bounded smooth domain of \mathbb{R}^N , $m \in L^\infty(\Omega)$ is a non-negative weight function and $f : \mathbb{R} \rightarrow \mathbb{R}$ is a C^1 function. Here $\mathcal{A}_{p(x)}u := \operatorname{div}\left(\alpha(x, u)\langle A\nabla u, \nabla u \rangle^{\frac{p(x)-2}{2}} A\nabla u\right)$ and will be called $\mathcal{A}_{p(x)}$ -Laplace operator where $A: \bar{\Omega} \rightarrow R^{N^2}$ is a symmetric matrix function with $a_{ij}(x) \in L^\infty(\Omega) \cap C^1(\bar{\Omega})$ and satisfy:

$$(1.4) \quad \langle A\xi, \xi \rangle = \sum_{i,j=1}^N a_{ij}(x)\xi_i\xi_j \geq |\xi|^2, \forall x \in \bar{\Omega}, \xi \in R^N,$$

where $\langle \cdot, \cdot \rangle$ denotes the scalar product on R^N , and $\alpha: \Omega \times R \rightarrow (0, \infty)$ is a *Carathéodory* function and for almost every $x \in \Omega$ and every $t \in R$ we have $\lambda \leq \alpha(x, t) \leq \Lambda$ for some positive λ and Λ . The $\mathcal{A}_{p(x)}$ -Laplace operator represents a generalization of the $p(x)$ -Laplace operator, i.e. $\Delta_{p(x)}u = \operatorname{div}(|\nabla u|^{p(x)-2} \cdot \nabla u)$, which is obtained in the case when $A = Id$ and $\alpha \equiv 1$.

In the last few decades, special attention has been paid to $p(x)$ -Laplace type operators since they can model with sufficient accuracy the phenomena arising from the study of electrorheological fluids [16, 17], image restoration [6], mathematical biology [11], dielectric breakdown, electrical resistivity and polycrystal plasticity [4, 5]. In a similar context, we note that a collection of results obtained in the field of partial differential equations involving $p(x)$ -Laplace type operators can be found in the survey paper by Harjulehto et al. [12]. Finally, we recall that in the case when $p(x)$ is a constant function, problems involving \mathcal{A}_p -Laplace type operators have been widely studied. In this regard we point out the papers by Alvino et al. [2] and El Khalil et al. [8]

and the references therein. In a recent paper [14], the authors established the existence of solutions for a partial differential equation involving the $\mathcal{A}_{p(x)}$ -Laplace operator by using the Schauder's fixed point theorem combined with adequate variational arguments.

To discuss problem (1.3), we need some theory on $W_0^{1,p(x)}(\Omega)$ which is called variable exponent Sobolev space. Firstly we state some basic properties of spaces $W_0^{1,p(x)}(\Omega)$ which will be used later (for details, see [9, 10]). Denote by $\mathbf{S}(\Omega)$ the set of all measurable real functions defined on Ω . Two functions in $\mathbf{S}(\Omega)$ are considered as the same element of $\mathbf{S}(\Omega)$ when they are equal almost everywhere. Write

$$C_+(\bar{\Omega}) = \{h : h \in C(\bar{\Omega}), h(x) > 1 \text{ for any } x \in \bar{\Omega}\},$$

$$h^- := \min_{\bar{\Omega}} h(x), \quad h^+ := \max_{\bar{\Omega}} h(x) \quad \text{for every } h \in C_+(\bar{\Omega}).$$

Define

$$L^{p(x)}(\Omega) = \{u \in \mathbf{S}(\Omega) : \int_{\Omega} |u(x)|^{p(x)} dx < +\infty \text{ for } p \in C_+(\bar{\Omega})\}$$

with the norm

$$|u|_{L^{p(x)}(\Omega)} = |u|_{p(x)} = \inf\{\lambda > 0 : \int_{\Omega} \left|\frac{u(x)}{\lambda}\right|^{p(x)} dx \leq 1\},$$

and

$$W^{1,p(x)}(\Omega) = \{u \in L^{p(x)}(\Omega) : |\nabla u| \in L^{p(x)}(\Omega)\}$$

with the norm

$$\|u\|_{W^{1,p(x)}(\Omega)} = |u|_{L^{p(x)}(\Omega)} + |\nabla u|_{L^{p(x)}(\Omega)}.$$

Denote by $W_0^{1,p(x)}(\Omega)$ the closure of $C_0^\infty(\Omega)$ in $W^{1,p(x)}(\Omega)$.

Theorem 1.1 ([10]). *The spaces $L^{p(x)}(\Omega)$, $W^{1,p(x)}(\Omega)$ and $W_0^{1,p(x)}(\Omega)$ are separable and reflexive Banach spaces.*

2. Main results

Define $\varphi(s) = |s|^{p(x)-1}s$, $s \in \mathbb{R}$ and $\Phi(\xi) = |\xi|^{p(x)-1}\xi$, $\xi \in \mathbb{R}^n$, for $p(x) > 0$. We begin with the following lemma.

Lemma 2.1 ([13]). *For $X, Y \in \mathbb{R}^n$, we have*

$$F(X, Y) := \langle X, \Phi(X) \rangle + \alpha \langle Y, \Phi(Y) \rangle - (\alpha + 1) \langle X, \Phi(Y) \rangle \geq 0,$$

where the equality holds if and only if $X = Y$.

Next we present our main result.

Theorem 2.2. *Let $v > 0$ and $u \geq 0$ be two non-constant differentiable functions in Ω . For all $x \in \Omega$ define*

$$\begin{aligned} L(u, v) &= \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)}{2}} \\ &+ (p(x) - 1) \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \frac{u^{p(x)}}{v^{p(x)}} \nabla v \rangle \\ &- p(x) \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \frac{u^{p(x)-1}}{v^{p(x)-1}} \nabla u \rangle, \end{aligned}$$

$$R(u, v) = \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)}{2}} - \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \nabla \left(\frac{u^p}{v^{p-1}} \right) \rangle.$$

Then $L(u, v) = R(u, v) \geq 0$. Moreover $L(u, v) = 0$ a.e. in Ω if and only if $\nabla(\frac{u}{v}) = 0$ a.e. in Ω .

Proof. Expanding $R(u, v)$ by direct calculation one easily sees that $L(u, v) = R(u, v)$. To show $L(u, v) \geq 0$ we proceed as follow:

For simplicity, we let $\alpha(x, u) = \alpha(x, v) = 1$. Since A is positive definite, there exists a square root \sqrt{A} of A which is positive definite. We easily obtain

$$\langle A \nabla u, \nabla u \rangle = |\sqrt{A} \nabla u|^2.$$

Hence we get

$$\begin{aligned} L(u, v) &= |\sqrt{A} \nabla u|^{p(x)} + (p(x) - 1) |\sqrt{A} \frac{u}{v} \nabla v|^{p(x)} \\ &- p(x) |\sqrt{A} \frac{u}{v} \nabla v|^{p(x)-2} \langle \sqrt{A} \frac{u}{v} \nabla v, \sqrt{A} \nabla u \rangle. \end{aligned}$$

which is nonnegative (from Lemma 2.1 and cf. [20, p. 85]). Equality holds if $\sqrt{A} \frac{u}{v} \nabla v = \sqrt{A} \nabla u$. Since \sqrt{A} is positive definite, it follows from $\sqrt{A} \frac{u}{v} \nabla v = \sqrt{A} \nabla u$ that $\nabla(\frac{u}{v}) = 0$. □

3. Applications

3.1. Sturmian Theory. First we give a nonlinear version of Sturm-type comparison result for $\mathcal{A}_{p(x)}$ -Laplacian operator. We start by definition of weak solutions of (1.3).

Definition 3.1. By the weak solution of (1.3) we mean any $u \in W_0^{1,p(x)}(\Omega)$ which satisfies

$$\int_{\Omega} \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)-2}{2}} \langle A \nabla u, \nabla \phi \rangle dx = \int_{\Omega} m(x) |u|^{p(x)-2} u \phi dx,$$

for any $\phi \in W_0^{1,p(x)}(\Omega)$.

Theorem 3.2. *Let $m_1 < m_2$ be two weight functions of (1.3) and u be a positive solution of (1.3) for $m = m_1$. Then any nontrivial solution v of (1.3) for $m = m_2$, must change sign.*

Proof. Suppose the contrary. We may assume that there exists a solution $v > 0$ of (1.3) in Ω . Then by Picone’s identity we have

$$\begin{aligned} 0 &\leq \int_{\Omega} L(u, v) = \int_{\Omega} R(u, v) \\ &= \int_{\Omega} \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)}{2}} - \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \nabla \left(\frac{u^p}{v^{p-1}} \right) \rangle \\ &= \int_{\Omega} m_1(x) u^{p(x)} - m_2(x) u^{p(x)} \\ &= \int_{\Omega} (m_1 - m_2) u^{p(x)} < 0, \end{aligned}$$

which is a contradiction. Hence, v changes sign in Ω . □

3.2. Nonlinear elliptic system involving the $\mathcal{A}_{p(x)}$ -Laplacian. Let us consider the following coupled nonlinear elliptic system:

$$\begin{aligned} & -\operatorname{div} \left(\alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)-2}{2}} A \nabla u \right) = v^{p(x)-1} \quad \text{in } \Omega \\ (3.1) \quad & -\operatorname{div} \left(\alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} A \nabla v \right) = \frac{v^{2(p(x)-1)}}{u^{p(x)-1}} \quad \text{in } \Omega \\ & u > 0, \quad v > 0 \quad \text{in } \Omega \\ & u = 0, \quad v = 0 \quad \text{on } \partial\Omega. \end{aligned}$$

We will show that Picone’s Identity yields a linear relationship between u and v .

Theorem 3.3. *Let (u, v) be a weak solution of (3.1). Then $u = c_1 v$ where c_1 is a constant.*

Proof. Let (u, v) be the weak solution of (3.1). Now for any ϕ_1 and ϕ_2 in $W_0^{1,p(x)}(\Omega)$, we have

$$(3.2) \quad \int_{\Omega} \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)-2}{2}} \langle A \nabla u, \nabla \phi_1 \rangle dx = \int_{\Omega} v^{p(x)-1} \phi_1 dx,$$

$$(3.3) \quad \int_{\Omega} \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \nabla \phi_2 \rangle dx = \int_{\Omega} \frac{v^{2(p(x)-1)}}{u^{p(x)-1}} \phi_2 dx.$$

Choosing $\phi_1 = u$ and $\phi_2 = \frac{u^{p(x)}}{v^{p(x)-1}}$ in (3.2) and (3.3) we obtain

$$\begin{aligned} & \int_{\Omega} \alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)}{2}} dx \\ &= \int_{\Omega} uv^{p(x)-1} dx \\ &= \int_{\Omega} \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \nabla \left(\frac{u^{p(x)}}{v^{p(x)-1}} \right) \rangle dx. \end{aligned}$$

Hence we have

$$\begin{aligned} \int_{\Omega} R(u, v) dx &= \int_{\Omega} \left(\alpha(x, u) \langle A \nabla u, \nabla u \rangle^{\frac{p(x)}{2}} \right. \\ &\quad \left. - \alpha(x, v) \langle A \nabla v, \nabla v \rangle^{\frac{p(x)-2}{2}} \langle A \nabla v, \nabla \left(\frac{u^{p(x)}}{v^{p(x)-1}} \right) \rangle \right) dx \\ &= 0. \end{aligned}$$

By the positivity of $R(u, v)$ we have that $R(u, v) = 0$ and hence

$$\nabla \left(\frac{u}{v} \right) = 0$$

which gives $u = c_1 v$ where c_1 is a constant. \square

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