# METRIC AND PERIODIC LINES IN THE POINCARÉ BALL MODEL OF HYPERBOLIC GEOMETRY 

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#### Abstract

In this paper, we prove that every metric line in the Poincaré ball model of hyperbolic geometry is exactly a classical line of it. We also prove nonexistence of periodic lines in the Poincaré ball model of hyperbolic geometry.


## 1. Introduction

A real distance space $\Delta=(\mathbb{S}, d)$ is a non-empty set $\mathbb{S}$ together with a mapping $d: \mathbb{S} \times \mathbb{S} \rightarrow \mathbb{R}$. The subset $k$ of $\mathbb{S}$ is called a metric line of $\Delta$ if, and only if, there exists a bijection $f: k \rightarrow \mathbb{R}$ such that ([2])

$$
d(x, y)=|f(x)-f(y)| \quad \text { for all } x, y \in k .
$$

The subset $k$ of $\mathbb{S}$ is called a $\rho$-periodic line of $\Delta$ if and only if, there exists a bijection $f: k \rightarrow[0, \rho[$ with

$$
d(x, y)= \begin{cases}(|f(x)-f(y)|, & \text { if }|f(x)-f(y)| \leq \rho / 2 \\ \rho-|f(x)-f(y)|, & \text { if }|f(x)-f(y)|>\rho / 2\end{cases}
$$

for all $x, y \in k$.

In [1], Benz determined the metric lines of hyperbolic geometry, the metric and periodic lines of Euclidean geometry, the $2 \pi$-periodic lines of spherical geometry, and the $\pi$-periodic lines of elliptic geometry. The problems to determine all metric lines and periodic lines of $\Delta$ is given by Benz as follows:

Problem 1.1. Determine all injective functions $x: \mathbb{R} \rightarrow \mathbb{S}$ such that

$$
\begin{equation*}
d(x(\xi), x(\eta))=|\xi-\eta| \tag{1.1}
\end{equation*}
$$

holds true for all real $\xi, \eta$.
Problem 1.2. Determine all injective functions $x:[0, \rho[\rightarrow \mathbb{S}$ such that

$$
d(x(\xi), x(\eta))= \begin{cases}|\xi-\eta|, & \text { if }|\xi-\eta| \leq \rho / 2  \tag{1.2}\\ \rho-|\xi-\eta|, & \text { if }|\xi-\eta|>\rho / 2\end{cases}
$$

holds true for all $\xi, \eta \in[0, \rho[$.
Moreover, Benz proved in his paper that the distance space $(k, d)$ is a metric space for every metric and $\rho$-periodic line $k$ of $\Delta=(\mathbb{S}, d)$. Throughout the paper, we only deal with Poincaré ball model of hyperbolic geometry. In the Poincaré ball model, also known as the conformal ball model, a gyroline (hyperbolic line) is an Euclidean semicircular arc that intersects the boundary of the ball orthogonally.

## 2. Möbius Transformations of the disc

In complex analysis Möbius transformations are well known and fundamental. The most general Möbius transformation of the complex open unit disc

$$
\mathbb{D}=\{z \in \mathbb{C}:|z|<1\}
$$

in the complex $z$-plane

$$
z \rightarrow e^{i \theta} \frac{z_{0}+z}{1+\overline{z_{0}} z}=e^{i \theta}\left(z_{0} \oplus z\right)
$$

defines the Möbius addition $\oplus$ in the disc, allowing the Möbius transformation of the disc to be viewed as Möbius left gyrotranslation

$$
z \rightarrow z_{0} \oplus z=\frac{z_{0}+z}{1+\overline{z_{0}} z}
$$

followed by rotation. Here $\theta$ is a real number, $z_{0} \in \mathbb{D}$, and $\overline{z_{0}}$ is the complex conjugate of $z_{0}$. Möbius substraction " $\ominus$ " is given by $a \ominus z=$ $a \oplus(-z)$, clearly $z \ominus z=0$ and $\ominus z=-z$. Möbius addition $\oplus$ is a
binary operation in the disc $\mathbb{D}$, but clearly it is neither commutative nor associative. Möbius addition $\oplus$ gives rise to the groupoid $(\mathbb{D}, \oplus)$ studied by Ungar in several books including [5, 6, 9, 10]. Möbius addition is similar to the common vector addition + in Euclidean plane geometry. Since Möbius addition $\oplus$ is neither commutative nor associative, the groupoid $(\mathbb{D}, \oplus)$ is not a group but it has a group-like structure that we present below.

The breakdown of commutativity in Möbius addition is "repaired" by the introduction of gyration,

$$
\text { gyr }: \mathbb{D} \times \mathbb{D} \rightarrow \operatorname{Aut}(\mathbb{D}, \oplus)
$$

given by the equation

$$
\begin{equation*}
\operatorname{gyr}[a, b]=\frac{a \oplus b}{b \oplus a}=\frac{1+a \bar{b}}{1+\bar{a} b}, \tag{2.1}
\end{equation*}
$$

where $\operatorname{Aut}(\mathbb{D}, \oplus)$ is the automorphism group of the groupoid $(\mathbb{D}, \oplus)$. Therefore, the gyrocommutative law of Möbius addition $\oplus$ follows from the definition of gyration in (2.1),

$$
\begin{equation*}
a \oplus b=\operatorname{gyr}[a, b](b \oplus a) . \tag{2.2}
\end{equation*}
$$

Coincidentally, the gyration gyr $[a, b]$ that repairs the breakdown of the commutative law of $\oplus$ in (2.2), repairs the breakdown of the associative law of $\oplus$ as well, giving rise to the respective left and right gyroassociative laws

$$
\begin{aligned}
& a \oplus(b \oplus c)=(a \oplus b) \oplus \operatorname{gyr}[a, b] c \\
& (a \oplus b) \oplus c=a \oplus(b \oplus \operatorname{gyr}[b, a] c)
\end{aligned}
$$

for all $a, b, c \in \mathbb{D}$.
Definition 2.1. A groupoid $(\mathbb{G}, \oplus)$ is a gyrogroup if its binary operation satisfies the following axioms
(G1) $0 \oplus a=0$, left identity property
(G2) $\ominus a \oplus a=0$, left inverse property
(G3) $a \oplus(b \oplus c)=(a \oplus b) \oplus \operatorname{gyr}[a, b] c$, left gyroassociative law
(G4) $\operatorname{gyr}[a, b] \in \operatorname{Aut}(\mathbb{G}, \oplus)$, gyroautomorphism
(G5) $\operatorname{gyr}[a, b]=\operatorname{gyr}[a \oplus b, b]$, left loop property
for all $a, b, c \in \mathbb{G}$.
Additionally, if the binary operation " $\oplus$ " obeys the gyrocommutative law
(G6) $a \oplus b=\operatorname{gyr}[a, b](b \oplus a)$, gyrocommutative law
for all $a, b, c \in \mathbb{G}$, then $(\mathbb{G}, \oplus)$ called a gyrocommutative gyrogroup. It is easy to see that $-a=\ominus a$, for all elements $a$ of $\mathbb{G}$.

Clearly, with these properties, one can now readily check that the Möbius complex disc groupoid $(\mathbb{D}, \oplus)$ is a gyrocommutative gyrogroup.

The axioms in Definition 2.1 imply the right identity property, the right inverse property, the right gyyroassociative law and the right loop property. We refer readers to [5] and [6] for more details about gyrogroups.

Now define the secondary binary operation $\boxplus$ in $\mathbb{G}$ by

$$
a \boxplus b=a \oplus \operatorname{gyr}[a, \oplus b] b .
$$

The primary and secondary operations of $\mathbb{G}$ are collectively called the dual operations of gyrogroups.

Let $a, b$ be two elements of a gyrogroup $(\mathbb{G}, \oplus)$. Then the unique solution of the equation

$$
a \oplus x=b
$$

for the unknown $x$ is

$$
x=\Theta a \oplus b
$$

and the unique solution of the equation

$$
x \oplus a=b
$$

for the unknown $x$ is

$$
x=b \boxminus a .
$$

## 3. Möbius gyrogroups: from the disc to the ball

Let us identify complex numbers of the complex plane $\mathbb{C}$ with vectors of the Euclidean plane $\mathbb{R}^{2}$ in the usual way:

$$
\mathbb{C} \ni u=u_{1}+i u_{2}=\left(u_{1}, u_{2}\right)=\mathbf{u} \in \mathbb{R}^{2} .
$$

Then the equations

$$
\begin{align*}
\mathbf{u} \cdot \mathbf{v} & =\operatorname{Re}(\bar{u} v) \\
\|\mathbf{u}\| & =|u| \tag{3.1}
\end{align*}
$$

give the inner product and the norm in $\mathbb{R}^{2}$, so that Möbius addition in the disc $\mathbb{D}$ of $\mathbb{C}$ becomes Möbius addition in the disc
$\mathbb{R}_{1}^{2}=\left\{\mathbf{v} \in \mathbb{R}^{2}:\|\mathbf{v}\|<1\right\}$ of $\mathbb{R}^{2}$. In fact we get from Eq.(3.1) that

$$
\begin{align*}
u \oplus v & =\frac{u+v}{1+\bar{u} v} \\
& =\frac{(1+u \bar{v})(u+v)}{(1+\bar{u} v)(1+u \bar{v})} \\
& =\frac{\left(1+\bar{u} v+u \bar{v}+|v|^{2}\right) u+\left(1-|u|^{2}\right) v}{1+\bar{u} v+u \bar{v}+|u|^{2}|v|^{2}}  \tag{3.2}\\
& =\frac{\left(1+2 \mathbf{u} \cdot \mathbf{v}+\|\mathbf{v}\|^{2}\right) \mathbf{u}+\left(1-\|\mathbf{u}\|^{2}\right) \mathbf{v}}{1+2 \mathbf{u} \cdot \mathbf{v}+\|\mathbf{u}\|^{2}\|\mathbf{v}\|^{2}} \\
& =\mathbf{u} \oplus \mathbf{v}
\end{align*}
$$

for all $u, v \in \mathbb{D}$ and all $\mathbf{u}, \mathbf{v} \in \mathbb{R}_{1}^{2}$.

## 4. Möbius addition in the ball

Let $\mathbb{V}$ be any inner-product space and

$$
\mathbb{V}_{s}=\{v \in \mathbb{V}:\|v\|<s\}
$$

be the open ball of $\mathbb{V}$ with radius $s>0$. Möbius addition in $\mathbb{V}_{s}$ is motivated by Eq.(3.2). It is given by the equation

$$
\begin{equation*}
\mathbf{u} \oplus \mathbf{v}=\frac{\left(1+\left(2 / s^{2}\right) \mathbf{u} \cdot \mathbf{v}+\left(1 / s^{2}\right)\|\mathbf{v}\|^{2}\right) \mathbf{u}+\left(1-\left(1 / s^{2}\right)\|\mathbf{u}\|^{2}\right) \mathbf{v}}{1+\left(2 / s^{2}\right) \mathbf{u} \cdot \mathbf{v}+\left(1 / s^{4}\right)\|\mathbf{u}\|^{2}\|\mathbf{v}\|^{2}} \tag{4.1}
\end{equation*}
$$

where $\cdot$ and $\|\cdot\|$ are the inner product and norm that the ball $\mathbb{V}_{s}$ inherits from its space $\mathbb{V}$ and where, ambiguously, + denotes both addition of real numbers on the real line and addition of vectors in $\mathbb{V}$. Without loss of generality, we may assume that $s=1$ in (4.1). However we prefer to keep $s$ as a free positive parameter in order to exhibit the results that in the limit as $s \rightarrow \infty$, the ball $\mathbb{V}_{s}$ expands the whole of its real inner product space $\mathbb{V}$, and Möbius addition $\oplus$ reduces to vector addition + in $\mathbb{V}$, i.e.,

$$
\lim _{s \rightarrow \infty} \mathbf{u} \oplus \mathbf{v}=\mathbf{u}+\mathbf{v}
$$

and

$$
\lim _{s \rightarrow \infty} \mathbb{V}_{s}=\mathbb{V}
$$

Möbius scalar multiplication is given by the equation

$$
\begin{aligned}
r \otimes \mathbf{v} & =s \frac{(1+\|\mathbf{v}\| / s)^{r}-(1-\|\mathbf{v}\| / s)^{r}}{(1+\|\mathbf{v}\| / s)^{r}+(1-\|\mathbf{v}\| / s)^{r}} \frac{\mathbf{v}}{\|\mathbf{v}\|} \\
& =s \tanh \left(r \tanh ^{-1}\|\mathbf{v}\| / s\right) \frac{\mathbf{v}}{\|\mathbf{v}\|},
\end{aligned}
$$

where $r \in \mathbb{R}, \mathbf{u}, \mathbf{v} \in \mathbb{V}_{c}, \mathbf{v} \neq 0$ and $r \otimes 0=0$. Möbius scalar multiplication possesses the following properties:
(P1) $n \otimes \mathbf{v}=v \oplus v \oplus \cdots \oplus v,(n$-terms $)$
(P2) $\left(r_{1}+r_{2}\right) \otimes \mathbf{v}=r_{1} \otimes \mathbf{v} \oplus r_{2} \otimes \mathbf{v}$, scalar distribute law
(P3) $\left(r_{1} r_{2}\right) \otimes \mathbf{v}=r_{1} \otimes\left(r_{2} \otimes \mathbf{v}\right)$, scalar associative law
(P4) $r \otimes\left(r_{1} \otimes \mathbf{v} \oplus r_{2} \otimes \mathbf{v}\right)=r \otimes\left(r_{1} \otimes \mathbf{v}\right) \oplus r \otimes\left(r_{2} \otimes \mathbf{v}\right)$, monodistribute law
(P5) $\|r \otimes \mathbf{v}\|=|r| \otimes\|\mathbf{v}\|$, homogeneity property
(P6) $\frac{|r| \otimes \mathbf{v}}{\|r \otimes \mathbf{v}\|}=\frac{\mathbf{v}}{\|\mathbf{v}\|}$, scaling property
(P7) $\operatorname{gyr}[\mathbf{a}, \mathbf{b}](r \otimes \mathbf{v})=r \otimes \operatorname{gyr}[\mathbf{a}, \mathbf{b}] \mathbf{v}$, gyroautomorphism property
(P8) $1 \otimes \mathbf{v}=\mathbf{v}$, multiplicative unit property
Definition 4.1 (Möbius Gyrovector Spaces). Let $\left(\mathbb{V}_{s}, \oplus\right)$ be a Möbius gyrogroup equipped with scalar multiplication $\otimes$. The triple $\left(\mathbb{V}_{s}, \oplus, \otimes\right)$ is called a Möbius gyrovector space.

## 5. Möbius Geodesics and Angles

As it is well known from Euclidean geometry, the straight line passing through two given points $A$ and $B$ of a vector space $\mathbb{R}^{n}$ can be represented by the expression

$$
A+(-A+B) \xi \quad \text { for } \xi \in \mathbb{R}
$$

Obviously it passes through $A$ when $\xi=0$, and through $B$ when $\xi=1$.
In full analogy with Euclidean geometry, the unique Möbius geodesic passing through two given points $A$ and $B$ of a Möbius gyrovector space $\left(\mathbb{V}_{s}, \oplus, \otimes\right)$ is represented by the parametric gyrovector equation

$$
L_{A B}=A \oplus(\ominus A \oplus B) \otimes \xi
$$

with parameter $\xi \in \mathbb{R}$. It passes through $A$ when $\xi=0$, and through $B$ when $\xi=1$. The gyroline $L_{A B}$ turns out to be a circular arc that intersects the boundary of the ball $\mathbb{V}_{s}$ orthogonally. The gyromidpoint $M_{A B}$ of the points $A$ and $B$ corresponds to the parameter $\xi=1 / 2$ of
the gyroline $L_{A B}$, see [6],

$$
M_{A B}=A \oplus(\ominus A \oplus B) \otimes \frac{1}{2} .
$$

The measure of a Mobius angle between two intersecting geodesic rays equals the measure of the Euclidean angle between corresponding intersecting tangent lines, as shown in Fig 1 below. The gyrodistance


Figure 1. The unique 2-dimensional geodesics that pass through two given points and the hyperbolic angle between two intersecting geodesics rays in a Möbius gyrovector plane $\left(\mathbb{R}_{s}^{2}, \oplus, \otimes\right)$. For the non-zero gyrovectors $\ominus A \oplus B$ and $\ominus A \oplus C$ or equivalently $\ominus A \oplus E$ and $\ominus A \oplus D$ the measure of the gyroangle $\alpha$ given by the equation $\cos \alpha=\frac{\ominus A \oplus B}{\|\ominus A \oplus B\|} \cdot \frac{\ominus A \oplus C}{\|\ominus A \oplus C\|}$ or equivalently by the equation $\cos \alpha=\frac{\ominus A \oplus E}{\|\ominus A \oplus E\|} \cdot \frac{\ominus A \oplus D}{\|\ominus A \oplus D\|}$
remains invariant under automorphisms and left gyrotranslations (see [6]).
Definition 5.1. The hyperbolic distance function in $\left(\mathbb{V}_{s}, \oplus, \otimes\right)$, is given by the equation

$$
d(A, B)=\|A \oplus B\| \quad \text { for } A, B \in \mathbb{V}_{s}
$$

In [1], W. Benz stressed that in spherical and elliptic Geometries there do not exist metric lines, since for those geometrics the left-hand side of (1.1), is bounded, but not the right-hand side. By the same reason there do not exist metric lines in Poincaré ball model of hyperbolic geometry when we let

$$
\mathbb{S}:=\{X \in \mathbb{V}:\|X\|<1\} \quad \text { and } \quad d(A, B)=\|A \ominus B\| .
$$

## 6. Metric and Periodic Lines in Poincaré Ball Model of Hyperbolic Geometry

Let $\mathbb{V}$ be a real inner-product space of arbitrary finite or infinite dimension $\geq 2$. Define the real distance space $\Delta=(\mathbb{S}, d)$ by

$$
\mathbb{S}:=\{X \in \mathbb{V}:\|X\|<1\} \quad \text { and } \quad \tanh d(X, Y)=\|X \oplus Y\|
$$

for all $X, Y \in \mathbb{S}$. The classical lines of $\Delta$ are given by

$$
\{P \oplus Q \otimes \xi: \xi \in \mathbb{R}\}
$$

for $P, Q \in \mathbb{S}$ such that $\|Q\|=\tanh 1$.
Theorem 6.1. The metric lines of $\Delta$ are exactly the classical lines of $\Delta$.

Proof. Let $P, Q$ be elements of $\mathbb{S}$ satisfying $\|Q\|=\tanh 1$. Then the function

$$
\begin{equation*}
x(\xi)=P \oplus Q \otimes \xi \tag{6.1}
\end{equation*}
$$

is injective and

$$
d(x(\xi), x(\eta))=|\xi-\eta|
$$

holds true for all $\xi, \eta \in \mathbb{R}$. Hence (6.1) is a metric line of $\Delta$.
Now, suppose that the function $x: \mathbb{R} \rightarrow \mathbb{S}$ solves the functional equation (1.1) for all $\xi, \eta \in \mathbb{R}$. Put $P:=x(0)$ and observe that

$$
x^{\prime}(\xi):=\ominus P \oplus x(\xi)
$$

is also a solution since

$$
\|(\ominus P \oplus x(\xi)) \ominus(\ominus P \oplus x(\eta))\|=\|x(\xi) \ominus x(\eta)\|
$$

holds true for all $\xi, \eta \in \mathbb{R}$. Put $Q:=x^{\prime}(1)$, then $x^{\prime}(0)=0$ and observe, by (1.1),

$$
\tanh |1-0|=\tanh 1=\left\|x^{\prime}(1) \ominus x^{\prime}(0)\right\|=\|Q\| .
$$

Since

$$
\tanh |\xi-0|=\tanh |\xi|=\left\|x^{\prime}(\xi) \ominus x^{\prime}(0)\right\|=\left\|x^{\prime}(\xi)\right\|
$$

for all $\xi \in \mathbb{R}$, and by (1.1), we get

$$
\tanh |\xi-\eta|=\left\|x^{\prime}(\xi) \ominus x^{\prime}(\eta)\right\|,
$$

i.e.,

$$
\begin{aligned}
& \frac{\tanh ^{2} \xi+\tanh ^{2} \eta-2 \tanh \xi \tanh \eta}{1+\tanh ^{2} \xi \tanh ^{2} \eta-2 \tanh \xi \tanh \eta}= \\
& \qquad \frac{\left\|x^{\prime}(\xi)\right\|^{2}+\left\|x^{\prime}(\eta)\right\|^{2}-2\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle}{1+\left\|x^{\prime}(\xi)\right\|^{2}\left\|x^{\prime}(\eta)\right\|^{2}-2\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle}
\end{aligned}
$$

and this implies $\tanh \xi \tanh \eta=\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle$. Hence

$$
\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle^{2}=\left\langle x^{\prime}(\xi), x^{\prime}(\xi)\right\rangle\left\langle x^{\prime}(\eta), x^{\prime}(\eta)\right\rangle
$$

and by Cauchy-Schwarz we get

$$
x^{\prime}(\xi)=\varphi(\xi) \otimes Q \quad \text { for all } \xi \in \mathbb{R}
$$

with

$$
\varphi(\xi)=\xi
$$

in view of $\tanh \xi \tanh \eta=\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle$. Thus $x(\xi)=P \oplus Q \otimes \xi$ must be a classical line.

Theorem 6.2. For all $\rho>0$, then there do not exist $\rho$-periodic lines in $\Delta$.

Proof. Assume that $x:[0, \rho[\rightarrow \mathbb{S}$ is a solution of (1.2), for a certain $\rho>0$. Put $A:=x(0)$ and observe $x^{\prime}(\xi):=\ominus A \oplus x(\xi)$ is also a solution. Obviously $x^{\prime}(0)=0$ and put $P:=x^{\prime}(\rho / 2)$. For all $0 \leq \xi \leq \rho / 2$, by (1.2),

$$
\tanh |\xi-0|=\tanh \xi=\left\|x^{\prime}(\xi) \ominus x^{\prime}(0)\right\|=\left\|x^{\prime}(\xi)\right\| .
$$

It follows that for all $0 \leq \xi, \eta \leq \rho / 2$,

$$
\tanh |\xi-\eta|=\left\|x^{\prime}(\xi) \ominus x^{\prime}(\eta)\right\|
$$

i.e.,

$$
\begin{aligned}
\frac{\tanh ^{2} \xi+\tanh ^{2} \eta-2 \tanh \xi \tanh \eta}{1+\tanh ^{2} \xi \tanh ^{2} \eta-2 \tanh \xi \tanh \eta} & = \\
& \frac{\left\|x^{\prime}(\xi)\right\|^{2}+\left\|x^{\prime}(\eta)\right\|^{2}-2\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle}{1+\left\|x^{\prime}(\xi)\right\|^{2}\left\|x^{\prime}(\eta)\right\|^{2}-2\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle}
\end{aligned}
$$

and this implies $\tanh \xi \tanh \eta=\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle$. Hence

$$
\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle^{2}=\left\langle x^{\prime}(\xi), x^{\prime}(\xi)\right\rangle\left\langle x^{\prime}(\eta), x^{\prime}(\eta)\right\rangle
$$

and by Cauchy-Schwarz we get

$$
x^{\prime}(\xi)=\varphi(\xi) \otimes P \quad \text { for all } \xi \in[0, \rho / 2],
$$

with

$$
\varphi(\xi)=\frac{2 \xi}{\rho}
$$

in view of $\tanh \xi \tanh \eta=\left\langle x^{\prime}(\xi), x^{\prime}(\eta)\right\rangle$. If $\rho / 2<\varsigma<\rho$, by (1.2),

$$
\tanh (\rho-|\varsigma-0|)=\left\|x^{\prime}(\varsigma) \ominus x^{\prime}(0)\right\|
$$

Moreover, by (1.2),

$$
\tanh (\varsigma-\rho / 2)=\left\|x^{\prime}(\varsigma) \ominus x^{\prime}(\rho / 2)\right\|
$$

This implies $\left\langle x^{\prime}(\varsigma), P\right\rangle^{2}=\left\langle x^{\prime}(\varsigma), x^{\prime}(\varsigma)\right\rangle\langle P, P\rangle$ and hence, by CauchySchwarz

$$
\left.x^{\prime}(\varsigma)=\delta(\varsigma) \otimes P \quad \text { for all } \varsigma \in\right] \rho / 2, \rho[
$$

with

$$
\delta(\varsigma)=\frac{2}{\rho}(\rho-\varsigma)
$$

in view of $\tanh \frac{\rho}{2} \tanh (\rho-\varsigma)=\left\langle x^{\prime}(\varsigma), P\right\rangle$. This yields $x^{\prime}(\rho / 4)=$ $x^{\prime}(3 \rho / 4)$, which contradicts

$$
\left|\frac{3 \rho}{4}-\frac{\rho}{4}\right|=d\left(x^{\prime}\left(\frac{3 \rho}{4}\right), x^{\prime}\left(\frac{\rho}{4}\right)\right)
$$

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