

**G-POSITIVE AND G-REPOSITIVE SOLUTIONS TO  
SOME ADJOINTABLE OPERATOR EQUATIONS OVER  
HILBERT  $C^*$ -MODULES**

G. J. SONG

Communicated by Abbas Salemi Parizi

**ABSTRACT.** Some necessary and sufficient conditions are given for the existence of a G-positive (G-repositive) solution of adjointable operator equations  $AX = C$ ,  $AXA^{(*)} = C$  and  $AXB = C$  over Hilbert  $C^*$ -modules, respectively. Moreover, the expressions of these general G-positive (G-repositive) solutions are also derived. Some of the findings of this paper extend some known results in the literature.

## 1. Introduction

Hilbert  $C^*$ -module is a natural generalization of a Hilbert space and a  $C^*$ -algebra. The basic idea was to consider modules over  $C^*$ -algebras instead of linear spaces and to allow the inner product to take values in a  $C^*$ -algebra. The structure was first used by Kaplansky [11] in 1952. Compared to the Hilbert spaces, there exist some differences when we deal with operators in a general Hilbert  $C^*$ -module  $\mathcal{H}$ , for instances, a closed topologically complemented submodule of  $\mathcal{H}$  may not be orthogonally complemented, meanwhile the fundamental Riesz representation theorem concerning the bounded linear functionals of  $\mathcal{H}$  may also be not

---

MSC(2010): Primary: 47A62; Secondary: 47B15; 47B65.

Keywords: Hilbert  $C^*$ -module, Generalized inverse, Operator equation.

Received: 2 July 2011, Accepted: 8 September 2012.

© 2013 Iranian Mathematical Society.

true. For more details of  $C^*$ -algebra and Hilbert  $C^*$ -modules, we refer the readers to [13, 21].

Let  $\mathfrak{A}$  be a  $C^*$ -algebra. An inner-product  $\mathfrak{A}$ -module is a linear space  $E$  which is a right  $\mathfrak{A}$ -module (with a scalar multiplication satisfying  $\lambda(xa) = x(\lambda a) = (\lambda x)a$  for  $x \in E, a \in \mathfrak{A}, \lambda \in \mathbb{C}$ ), together with a map  $E \times E \rightarrow \mathfrak{A}, (x, y) \rightarrow \langle x, y \rangle$  such that

- (1)  $\langle x, \alpha y + \beta z \rangle = \alpha \langle x, y \rangle + \beta \langle x, z \rangle$ ;
- (2)  $\langle x, ya \rangle = \langle x, y \rangle a$ ;
- (3)  $\langle x, y \rangle = \langle y, x \rangle^*$ ;
- (4)  $\langle x, x \rangle \geq 0$ , and  $\langle x, x \rangle = 0 \Leftrightarrow x = 0$

for any  $x, y, z \in E, \alpha, \beta \in \mathbb{C}$  and  $a \in \mathfrak{A}$ . An inner-product  $\mathfrak{A}$ -module  $E$  is called a (right) Hilbert  $\mathfrak{A}$ -module if it is complete with respect to the induced norm  $\|x\| = |\langle x, x \rangle|^{1/2}$ .

Assume that  $\mathcal{H}$  and  $\mathcal{K}$  are two Hilbert  $\mathfrak{A}$ -modules, and  $\mathfrak{B}(\mathcal{H}, \mathcal{K})$  is the set of all maps  $T: \mathcal{H} \rightarrow \mathcal{K}$  for which there is a map  $T^*: \mathcal{K} \rightarrow \mathcal{H}$  such that  $\langle Tx, y \rangle = \langle x, T^*y \rangle$ , for any  $x \in \mathcal{H}$  and  $y \in \mathcal{K}$ . We know that any element  $T$  of  $\mathfrak{B}(\mathcal{H}, \mathcal{K})$  is a bounded linear operator. We call  $\mathfrak{B}(\mathcal{H}, \mathcal{K})$  the set of adjointable operators from  $\mathcal{H}$  into  $\mathcal{K}$ . In case  $\mathcal{H} = \mathcal{K}$ ,  $\mathfrak{B}(\mathcal{H}, \mathcal{H})$  which we abbreviate to  $\mathfrak{B}(\mathcal{H})$ , is a  $C^*$ -algebra. An operator  $A \in \mathfrak{B}(\mathcal{H})$  is called Hermitian (or self-adjoint) if  $A^* = A$ , and positive if  $\langle Ax, x \rangle \geq 0$  for all  $x \in \mathcal{H}$ , we write  $A \geq 0$  if  $A$  is positive. The Moore-Penrose inverse of  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  is defined as the operator  $A^\dagger \in \mathfrak{B}(\mathcal{K}, \mathcal{H})$  satisfying the Penrose equations

$$AA^\dagger A = A, A^\dagger AA^\dagger = A^\dagger, (A^\dagger A)^* = A^\dagger A, (AA^\dagger)^* = AA^\dagger.$$

An operator  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  has the (unique) Moore-Penrose inverse if and only if  $A$  has closed range, or equivalently it is regular. The notations  $\mathcal{R}(A)$  and  $\mathcal{N}(A)$  stand for the range of  $A$  and the null space of  $A$ , respectively. For simplicity, we use  $L_A$  and  $R_A$  to stand for  $I - A^\dagger A$  and  $I - AA^\dagger$ , respectively.

As a generalization of Hermitian operator, the quasi-hermitian operator over the Hilbert space was given in Dieudonné [6] as:  $S$  is called a quasi-hermitian operator if there is a positive bounded operator  $V$  such that  $VS = S^*V$ . Recently, Sun and Ma [15] studied a new kind of generalized Hermitian operator:  $S$  is called a generalized Hermitian operator if there is an invertible operator  $V$  such that  $VS = S^*V$ . In fact, many authors have shown some results concerning generalized Hermitian operators, although they have not used the terminology (generalized Hermitian operators). Such as, Radjavi and Williams [14] proved that a

bounded linear operator on a finite-dimensional Hilbert space is generalized Hermitian iff it is the product of two Hermitian operators; Jiang [10] showed that for a normal operator  $S$  is generalized Hermitian iff it is the product of two Hermitian operators. Also he considered the case of hyponormal operators.

We are now interested in the following operators:

**Definition 1.1.** (1) Suppose  $\mathcal{H}, \mathcal{K}$  are two Hilbert  $\mathfrak{A}$ -modules,  $V \in \mathfrak{B}(\mathcal{H}), W \in \mathfrak{B}(\mathcal{K})$  are Hermitian invertible,  $\mathfrak{B}(\mathcal{H}, \mathcal{K})$  is the set of all maps  $A : \mathcal{H} \rightarrow \mathcal{K}$  for which there is a map  $A^{(*)} : \mathcal{K} \rightarrow \mathcal{H}$  such that

$$\langle Ax, y \rangle = \langle Vx, A^{(*)}W^{-1}y \rangle, \text{ for all } x \in \mathcal{H} \text{ and } y \in \mathcal{K}.$$

(2) An operator  $A \in \mathfrak{B}(\mathcal{H})$  is called *G-Hermitian (G-skew-Hermitian)* if

$$A = A^{(*)} = V^{-1}A^*V \quad (A = -A^{(*)} = -V^{-1}A^*V).$$

(3) An operator  $A \in \mathfrak{B}(\mathcal{H})$  is called *G-positive* if and only if  $A$  is G-Hermitian and  $\langle Ax, Vx \rangle \geq 0$  for all  $x \in \mathcal{H}$ .

Obviously, the class of G-positive operators (G-repositive operators), which of course contains the positive operators (repositive operators), is in fact much wider. Let  $\mathfrak{B}(\mathcal{H})_G$  be the set of all G-Hermitian elements of  $\mathfrak{B}(\mathcal{H})$ ,  $\mathfrak{B}(\mathcal{H})^{(+)}$  be the set of all G-positive elements of  $\mathfrak{B}(\mathcal{H})$ . Then for  $A, B \in \mathfrak{B}(\mathcal{H})$ ,

- (1)  $(AB)^{(*)} = B^{(*)}A^{(*)}$ ,
- (2)  $A \in \mathfrak{B}(\mathcal{H})_G$  if and only if  $VA = A^*V$ , for some invertible Hermitian operator  $V$ ,
- (3)  $A$  is regular, then  $(A^\dagger)^{(*)} = (A^{(*)})^\dagger, (L_A)^{(*)} = R_{A^{(*)}}$  and  $(R_A)^{(*)} = L_{A^{(*)}}$ ,
- (4)  $A \in \mathfrak{B}(\mathcal{H})^{(+)}$  and is regular, then  $A^\dagger \in \mathfrak{B}(\mathcal{H})^{(+)}$ .

Researches on the nonnegative definite and Re-nonnegative definite solutions to matrix equations, as well as the positive and Re-positive solutions of operator equations have been actively ongoing for many years. For instance, the nonnegative definite solutions to matrix equation

$$(1.1) \quad AXB = C$$

were studied by Khatri, Mitra [12] in 1976 and Zhang [24] in 2004, respectively. In 1998, Wang and Yang [20] derived the Re-nonnegative definite solution to matrix equation (1.1) by matrix decomposition. Recently, Arias and Gonzalez [1] studied the positive solutions to operator

equation (1.1). Under the assumption that the underlying space is finite-dimensional or the range of  $B$  is contained in the range of  $A^*$ , Xu et al. [23] proposed some solvability conditions for operator equation (1.1) to have a positive solution and a Re-positive solution, as well as some expressions of these solutions in the general setting of Hilbert  $C^*$ -modules. Some other results can be found in [22]-[7].

In fact, the positive (Re-positive) operator can be seen as a special case of G-positive (G-repositive) operator, therefore investigating the G-positive (G-repositive) solutions to some operator equations over Hilbert  $C^*$ -modules are very meaningful. So far, to our knowledge, there has been little information on either the G-positive or the G-repositive to adjointable operator equations over Hilbert  $C^*$ -modules. Then in this paper, we mainly consider the G-positive and G-repositive solutions to some classical adjointable operator equations over the Hilbert  $C^*$ -modules. This paper is organized as follows: In Section 2, we present some criteria for an adjointable operator to be G-positive (G-repositive). In Section 3, we show some necessary and sufficient conditions for the existence of a G-positive solution to some adjointable operator equations over Hilbert  $C^*$ -modules. The expressions of these general G-positive solutions are also derived. In Section 4, we show some necessary and sufficient conditions for the existence of a G-repositive solutions to some adjointable operator equations over Hilbert  $C^*$ -modules, as well as the general expressions of these solutions. We conclude the paper by proposing in Section 5 some further research topics.

## 2. Preliminaries

For any operator  $A \in \mathfrak{B}(\mathcal{H})$ , there exist two orthogonal projections  $P_1, P_2 = I - P_1$ , such that  $A$  can be expressed as

$$A = A_1 + A_2 + A_3 + A_4,$$

where

$$A_1 = P_1 A P_1^{(*)}, A_2 = P_1 A P_2^{(*)}, A_3 = P_2 A P_1^{(*)}, A_4 = P_2 A P_2^{(*)}.$$

The mapping  $\Psi : \mathfrak{B}(\mathcal{H}) \rightarrow \mathfrak{B}(\mathcal{H} \oplus \mathcal{H})$  is an algebra  $*$ -*monomorphism* where  $\mathfrak{B}(\mathcal{H} \oplus \mathcal{H})$  equipped with the usual matrix operations. Then we shall write  $A = \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix}$  with respect to  $P_1, P_2$ , and have the following results:

**Theorem 2.1.** *Suppose that  $A \in \mathfrak{B}(\mathcal{H})_G$  and has closed range. Then  $A \in \mathfrak{B}(\mathcal{H})^{(+)}$  if and only if the following conditions are satisfied:*

- (1)  $A_1 \in \mathfrak{B}(\mathcal{H})^{(+)}$ ,
- (2)  $A_1 A_1^\dagger A_2 = A_2$ ,
- (3)  $A_4 - A_3 A_1^\dagger A_2 \in \mathfrak{B}(\mathcal{H})^{(+)}$ .

*Proof.* Suppose that  $A \in \mathfrak{B}(\mathcal{H})^{(+)}$ , then there exists  $H = V^{-1} (A^* V)^{\frac{1}{2}}$  such that  $A = HVH^{(*)}$  and  $A_1 = P_1 A P_1^{(*)} = P_1 H V H^{(*)} P_1^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$ . In view of

$$\begin{aligned} A_1 A_1^\dagger &= P_1 H V (P_1 H)^{(*)} \left( P_1 H V (P_1 H)^{(*)} \right)^\dagger \\ &= P_1 H V (P_1 H)^{(*)} \left( (P_1 H)^{(*)} \right)^\dagger V^{-1} (P_1 H)^\dagger \\ &= P_1 H V \left( (P_1 H)^\dagger P_1 H \right)^{(*)} V^{-1} (P_1 H)^\dagger \\ &= P_1 H (P_1 H)^\dagger, \end{aligned}$$

we have

$$A_1 A_1^\dagger A_2 = P_1 H (P_1 H)^\dagger P_1 H V H^{(*)} P_2^{(*)} = A_2.$$

Finally,

$$\begin{aligned} &A_4 - A_2^{(*)} A_1^\dagger A_2 \\ &= P_2 A P_2^{(*)} - P_2 A P_1^{(*)} A_1^\dagger P_1 A P_2^{(*)} \\ &= P_2 H V H^{(*)} P_2^{(*)} - P_2 H V H^{(*)} P_1^{(*)} \left( P_1 H V H^{(*)} P_1^{(*)} \right)^\dagger P_1 H V H^{(*)} P_2^{(*)} \\ &= P_2 H V H^{(*)} P_2^{(*)} - P_2 H V H^{(*)} P_1^{(*)} \left( H^{(*)} P_1^{(*)} \right)^\dagger V^{-1} (P_1 H)^\dagger P_1 H V H^{(*)} P_2^{(*)} \\ &= P_2 H V \left( I - H^{(*)} P_1^{(*)} \left( H^{(*)} P_1^{(*)} \right)^\dagger (P_1 H V)^\dagger P_1 H V \right) H^{(*)} P_2^{(*)} \\ &= P_2 H \left( I - (P_1 H)^\dagger P_1 H \right) V \left( P_2 H \left( I - (P_1 H)^\dagger P_1 H \right) \right)^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}. \end{aligned}$$

On the contrary, suppose that (1), (2) and (3) are satisfied, then for any

$$h = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \mathcal{H} \oplus \mathcal{H}, \text{ let}$$

$$V_1 = \begin{bmatrix} V & 0 \\ 0 & V \end{bmatrix}, \quad x = \begin{pmatrix} -A_1^\dagger A_2 x_2 \\ x_2 \end{pmatrix}, \quad y = \begin{pmatrix} x_1 + A_1^\dagger A_2 x_2 \\ 0 \end{pmatrix},$$

then

$$\begin{aligned}
& \langle Ax, V_1y \rangle \\
&= y^* V_1 Ax \\
&= \begin{pmatrix} x_1^* + x_2^* (A_1^\dagger A_2)^* & 0 \end{pmatrix} \begin{bmatrix} V & 0 \\ 0 & V \end{bmatrix} \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} -A_1^\dagger A_2 x_2 \\ x_2 \end{pmatrix} \\
&= \begin{pmatrix} x_1^* + x_2^* (A_2^\dagger A_1)^* & 0 \end{pmatrix} \begin{bmatrix} V & 0 \\ 0 & V \end{bmatrix} \begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix} \begin{pmatrix} -A_1^\dagger A_2 x_2 \\ x_2 \end{pmatrix} \\
&= \begin{pmatrix} x_1^* V + x_2^* (A_2^\dagger A_1)^* V & 0 \end{pmatrix} \begin{pmatrix} 0 \\ A_4 x_2 - A_3 A_1^\dagger A_2 x_2 \end{pmatrix} = 0.
\end{aligned}$$

Since

$$\begin{aligned}
& \langle Ah, V_1h \rangle \\
&= \langle A(x+y), V_1(x+y) \rangle \\
&= \langle Ax, V_1x \rangle + \langle Ax, V_1y \rangle + \langle Ay, V_1x \rangle + \langle Ay, V_1y \rangle = \langle Ax, V_1x \rangle + \langle Ay, V_1y \rangle \\
&= \left\langle \begin{pmatrix} A_4 - A_3 A_1^\dagger A_2 \end{pmatrix} x_2, V_1 x_2 \right\rangle + \left\langle \begin{pmatrix} A_4 - A_3 A_1^\dagger A_2 \end{pmatrix} x_1, V_1 x_1 \right\rangle \geq 0,
\end{aligned}$$

then  $A \in \mathfrak{B}(\mathcal{H})^{(+)}$ .  $\square$

**Corollary 2.2.** *Suppose that  $A \in \mathfrak{B}(\mathcal{H})_G$  has closed range. Then  $A \in \mathfrak{B}(\mathcal{H})^{(+)}$  if and only if the following conditions are satisfied:*

- (1)  $A_4 \in \mathfrak{B}(\mathcal{H})^{(+)}$ ,
- (2)  $A_4 A_4^\dagger A_3 = A_3$ ,
- (3)  $A_1 - A_2 A_4^\dagger A_3 \in \mathfrak{B}(\mathcal{H})^{(+)}$ .

The general real part of  $A \in \mathfrak{B}(\mathcal{H})$  is defined by  $\text{G-Re } A = \frac{1}{2} (A + A^{(*)})$ . Then  $\text{G-Re } A$  is always G-Hermitian,  $\text{G-Re } A = A$  if and only if  $A \in \mathfrak{B}(\mathcal{H})_G$ , moreover,

$$\text{G-Re}(A \pm B) = \text{G-Re } A + \text{G-Re } B, \quad \text{G-Re}(X^{(*)}AX) = X^{(*)}(\text{G-Re } A)X.$$

An element  $A \in \mathfrak{B}(\mathcal{H})$  is called G-repositive if and only if  $\text{G-Re } A \in \mathfrak{B}(\mathcal{H})^{(+)}$ . Similarly, we can prove the following results.

**Theorem 2.3.** *Suppose that  $A \in \mathfrak{B}(\mathcal{H})$  and  $\text{G-Re } A$  has closed range. Then  $A + A^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$  if and only if the following conditions are satisfied:*

- (1)  $A_1 + A_1^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$ ,

- (2)  $(A_1 + A_1^{(*)}) (A_1 + A_1^{(*)})^\dagger (A_2 + A_2^{(*)}) = (A_2 + A_2^{(*)}),$
- (3)  $(A_4 + A_4^{(*)}) - (A_3 + A_3^{(*)}) (A_1 + A_1^{(*)})^\dagger (A_2 + A_2^{(*)}) \in \mathfrak{B}(\mathcal{H})^{(+)}$ .

**Corollary 2.4.** *Suppose that  $A \in \mathfrak{B}(\mathcal{H})$  and  $G\text{-Re } A$  has closed range. Then  $A + A^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$  if and only if the following conditions are satisfied:*

- (1)  $A_3 + A_3^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)},$
- (2)  $(A_3 + A_3^{(*)}) (A_3 + A_3^{(*)})^\dagger (A_4 + A_4^{(*)}) = (A_4 + A_4^{(*)}),$
- (3)  $(A_1 + A_1^{(*)}) - (A_2 + A_2^{(*)}) (A_4 + A_4^{(*)})^\dagger (A_3 + A_3^{(*)}) \in \mathfrak{B}(\mathcal{H})^{(+)}$ .

### 3. G-positive solution to some adjointable operator equations over Hilbert $C^*$ -modules

In this Section, we mainly consider some necessary and sufficient conditions for some adjointable operator equations to have a G-positive solution, we also give expressions of these solutions.

**Theorem 3.1.** *Let  $A, C \in \mathfrak{B}(\mathcal{H}_1, \mathcal{H}_2)$ ,  $A$  and  $CA^{(*)}$  have closed ranges. Then adjointable operator equation*

$$(3.1) \quad AX = C$$

*has a G-positive solution  $X \in \mathfrak{B}(\mathcal{H}_2)^{(+)}$  if and only if  $CA^{(*)} \in \mathfrak{B}(\mathcal{H}_1)^{(+)}$  and  $\mathcal{R}(C) \subseteq \mathcal{R}(CA^{(*)})$ . In this case, the general a G-positive solution of equation (3.1) can be expressed as*

$$(3.2) \quad X = C^{(*)} (CA^{(*)})^\dagger C + (I - A^\dagger A)U(I - A^\dagger A)^{(*)},$$

*where  $U \in \mathfrak{B}(\mathcal{H}_2)^{(+)}$  is arbitrary.*

*Proof.* Suppose that  $CA^{(*)}$  is G-positive, then  $(CA^{(*)})^\dagger$  and  $C^{(*)} (CA^{(*)})^\dagger C$  are G-positive. Noting that

$$AC^{(*)} (CA^{(*)})^\dagger C = CA^{(*)} (CA^{(*)})^\dagger C = C,$$

then  $C^{(*)} (CA^{(*)})^\dagger C$  is a G-positive solution to equation (3.1). For the other direction. Let  $X_0$  be a G-positive solution to equation (3.1). Then

$CA^{(*)} = AX_0A^{(*)}$  is  $G$ -positive, and

$$\begin{aligned}\mathcal{R}\left(CA^{(*)}\right) &= \mathcal{R}\left(AX_0A^{(*)}\right) \\ &= \mathcal{R}\left(AX_1V\left(AX_1\right)^{(*)}\right) \\ &= \mathcal{R}\left(AX_1\right) \supseteq \mathcal{R}\left(AX_0\right) \\ &= \mathcal{R}(C),\end{aligned}$$

where  $X_0 = X_1VX_1^{(*)}$  for some Hermitian invertible operator  $V \in \mathfrak{B}(\mathcal{H}_2)$ .

Next we only need to show that every  $G$ -positive of equation (3.1) can be expressed as (3.2). Suppose  $X_1$  is an arbitrary  $G$ -positive solution of equation (3.1), and denote  $X_0 = C^{(*)}\left(CA^{(*)}\right)^\dagger C$ . Then  $X_1 - X_0$  is a  $G$ -Hermitian solution to equation  $AX = 0$ , so there exist a  $G$ -Hermitian matrix  $T$  such that  $X_1 - X_0 = (I - A^\dagger A)T(I - A^\dagger A)^{(*)}$ . Choose  $Y = C\left(CA^{(*)}\right)^\dagger CC^\dagger A$ , then  $YX_0 = X_0$ , and  $YA^\dagger A = Y$ , so  $(I - Y)X_0 = 0$  and  $(I - Y)(I - A^\dagger A) = (I - A^\dagger A)$ . Therefore,

$$\begin{aligned}(I - Y)X_1(I - Y)^{(*)} &= (I - Y)X_1(I - Y)^{(*)} - (I - Y)X_0(I - Y)^{(*)} \\ &= (I - Y)(X_1 - X_0)(I - Y)^{(*)} \\ &= (I - Y)(I - A^\dagger A)T(I - A^\dagger A)^{(*)}(I - Y)^{(*)} \\ &= X_1 - X_0.\end{aligned}$$

Since  $(I - Y)X_1(I - Y)^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$ , then

$$X_1 = C^{(*)}\left(CA^{(*)}\right)^\dagger C + (I - A^\dagger A)T(I - A^\dagger A)^{(*)},$$

implying that every  $G$ -positive solution of equation (3.1) can be written as (3.2) with some proper choice of  $U$ .  $\square$

**Remark 3.2.** *Similarly, on the assumption that*

$$\begin{bmatrix} A \\ C^{(*)} \end{bmatrix} \text{ and } \begin{bmatrix} BA^{(*)} & BC \\ (AD)^{(*)} & D^{(*)}C \end{bmatrix}$$

*have closed ranges, then we can derive some necessary and sufficient conditions for adjointable operator equations  $AX = B$  and  $XC = D$  to have a common  $G$ -positive solution, as well as an expression for the common  $G$ -positive solutions.*



**Theorem 3.3.** *Let  $\mathcal{H}, \mathcal{K}$  be Hilbert  $C^*$ -modules. Assume that  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$ ,  $C \in \mathfrak{B}(\mathcal{K})$  such that  $A$  has closed range,  $C$  is  $G$ -Hermitian and  $\mathcal{R}(C) \subseteq \mathcal{R}(A)$ . Then equation*

$$(3.3) \quad AXA^{(*)} = C$$

*has a  $G$ -positive solution if and only if  $C$  is  $G$ -positive. If, in addition,  $C$  has closed range, the general  $G$ -positive solution of equation (3.3) can be expressed as*

$$(3.4) \quad X = X_2 + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)},$$

*with  $X_2 = A^\dagger C (A^\dagger)^{(*)}$  is a particular  $G$ -positive solution,  $E \in \mathfrak{B}(\mathcal{H})$  and  $F \in \mathfrak{B}(\mathcal{H})^{(+)}$  are arbitrary.*

*Proof.* When  $X$  is given as (3.4), and in view of the assumption  $\mathcal{R}(C) \subseteq \mathcal{R}(A)$  and  $C \in \mathfrak{B}(\mathcal{K})^{(+)}$ , then  $X \in \mathfrak{B}(\mathcal{H})^{(+)}$  and satisfies equation (3.3). Next we show that (3.4) provides the general  $G$ -positive solution. Assume that  $C$  has closed range and  $X$  is a  $G$ -positive solution to equation (3.3). Denote  $P_1 = A^\dagger A$ ,  $P_2 = (I - A^\dagger A)$ , then

$$X = X_1 + X_2 + X_3 + X_4 = P_1 X P_1^{(*)} + P_1 X P_2^{(*)} + P_2 X P_1^{(*)} + P_2 X P_2^{(*)}.$$

Combining the mapping  $\Psi : \mathfrak{B}(\mathcal{H}) \rightarrow \mathfrak{B}(\mathcal{H} \oplus \mathcal{H})$ ,  $X$  can be expressed as

$$X = \begin{bmatrix} X_1 & X_2 \\ X_3 & X_4 \end{bmatrix}.$$

Since

$$X_1 = P_1 X P_1^{(*)} = A^\dagger A X A^{(*)} (A^\dagger)^{(*)} = A^\dagger C (A^\dagger)^{(*)},$$

and note that  $C \in \mathfrak{B}(\mathcal{H})^{(+)}$ , then  $X_1 \in \mathfrak{B}(\mathcal{H})^{(+)}$ . Moreover,

$$\begin{aligned} X_1 A^{(*)} C^\dagger A X_1 &= A^\dagger C (A^\dagger)^{(*)} A^{(*)} C^\dagger A A^\dagger C (A^\dagger)^{(*)} \\ &= A^\dagger C V A A^\dagger C^\dagger A A^\dagger C V A = A^\dagger C C^\dagger C (A^\dagger)^{(*)} = X_1, \end{aligned}$$

thus  $X_1$  is regular and  $X_1^\dagger$  exists. It follows Theorem 2.1 that  $X_1 X_1^\dagger X_2 = X_2$  and  $X_4 - X_2^{(*)} X_1^\dagger X_2 \in \mathfrak{B}(\mathcal{H})^{(+)}$  are satisfied. Then we have  $X_2 =$

$X_1X_1^\dagger Y$ , where  $Y \in \mathfrak{B}(H)$  is arbitrary, and

$$\begin{aligned} X_4 - X_3^{(*)}X_1^\dagger X_2 &= X_4 - L_A E^{(*)} \left( X_2 X_2^\dagger \right)^* X_2^\dagger X_2 X_2^\dagger E L_A^{(*)} \\ &= X_4 - L_A E^{(*)} X_2^\dagger E L_A^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}. \end{aligned}$$

Then any arbitrary  $G$ -positive solution to equation (3.3) can be expressed as (3.4) with some proper choices of  $E$  and  $F$ .  $\square$

We can now prove the following result.

**Theorem 3.4.** *Let  $\mathcal{H}_i (i = 1, 2, \dots, 4)$  be Hilbert  $C^*$ -modules,  $A \in \mathfrak{B}(\mathcal{H}_1, \mathcal{H}_2)$ ,  $B \in \mathfrak{B}(\mathcal{H}_3, \mathcal{H}_1)$ ,  $C \in \mathfrak{B}(\mathcal{H}_3, \mathcal{H}_2)$ . Denote*

$$\begin{aligned} A_1 &= A^{(*)}V^{-1}A, B_1 \\ &= BVB^{(*)}, C_1 \\ &= A^{(*)}CB^{(*)}, M \\ &= A_1 + B_1, T \\ &= B_1M^\dagger C_1M^\dagger A_1. \end{aligned}$$

*Suppose that  $A, B, T$  and  $M$  have closed ranges. Then the consistent equation (1.1) has a  $G$ -positive solution if and only if*

$$(3.5) \quad \mathcal{R}(A_1M^\dagger C_1^{(*)}) \subseteq \mathcal{R}(T), \quad \mathcal{R}(B_1M^\dagger C_1) \subseteq \mathcal{R}(T).$$

*In this case, the general  $G$ -positive solution to equation (1.1) can be expressed as*

$$\begin{aligned} (3.6) \quad X &= M^\dagger \left( C_1 + C_1^{(*)} + Y + Z \right) \left( M^\dagger \right)^{(*)} + X_2 + X_2 X_2^\dagger E L_A^{(*)} \\ &\quad + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)}, \end{aligned}$$

*where  $X_2 = M^\dagger \left( C_1 + C_1^{(*)} + Y + Z \right) M^\dagger$ ,  $Y$  and  $Z$  are arbitrary  $G$ -positive solutions to equations*

$$(3.7) \quad Y M^\dagger B_1 = C_1 M^\dagger A_1, \quad A_1 M^\dagger Z = B_1 M^\dagger C_1,$$

*such that  $C_1 + C_1^{(*)} + Y + Z$  is  $G$ -positive,  $E \in \mathfrak{B}(\mathcal{H}_1)$  and  $F \in \mathfrak{B}(\mathcal{H}_1)^{(+)}$  are arbitrary.*

*Proof.* Suppose that equation (1.1) is consistent, then there is an  $X$  such that

$$T = B_1M^\dagger C_1M^\dagger A_1 = B_1M^\dagger A_1 X B_1M^\dagger A_1.$$

Moreover, since

$$\begin{aligned} A_1 &= A^{(*)}V^{-1}A \\ &= {}^{-1}A^*A \\ &= V^{-1}A^*VV^{-1}A \\ &= V^{-1}A^*V(V^{-1}A^*)^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}, \end{aligned}$$

and

$$\begin{aligned} B_1 &= BVB^{(*)} \\ &= BB^{(*)}V \\ &= BVV^{-1}B^*V \\ &= (BV)^{(*)}V^{-1}B^*V \in \mathfrak{B}(\mathcal{H})^{(+)}, \end{aligned}$$

thus

$$B_1M^\dagger A_1 = B_1(A_1 + B_1)^\dagger A_1 = A_1(A_1 + B_1)^\dagger B_1$$

is G-positive. When  $X$  is G-positive, there exist  $X_1$  such that

$$\begin{aligned} T &= B_1M^\dagger A_1 X B_1M^\dagger A_1 \\ &= B_1M^\dagger A_1 X_1 V \left( B_1M^\dagger A_1 X_1 \right)^{(*)} \in \mathfrak{B}(\mathcal{H}_1)^{(+)}. \end{aligned}$$

Further, we have

$$\begin{aligned} \mathcal{R}(B_1M^\dagger C_1) &= \mathcal{R}(B_1M^\dagger A_1 X B_1) \subseteq \mathcal{R}(B_1M^\dagger A_1 X_1 V) \\ &= \mathcal{R}\left( B_1M^\dagger A_1 X_1 V \left( B_1M^\dagger A_1 X_1 \right)^{(*)} \right) = \mathcal{R}(T) \end{aligned}$$

and  $\mathcal{R}(A_1M^\dagger C_1^{(*)}) \subseteq \mathcal{R}(T)$ .

For the sufficiency, we first show that when these conditions are true, G-positive solutions  $Y$  and  $Z$  to equations (3.7) can be so determined that

$$C_1 + C_1^{(*)} + Y + Z$$

is G-positive. Since  $T$  is G-positive and

$$\mathcal{R}(A_1M^\dagger C_1^{(*)}) \subseteq \mathcal{R}(T), \quad \mathcal{R}(B_1M^\dagger C_1) \subseteq \mathcal{R}(T),$$

then it follows from Theorem 3.1 that the general G-positive solutions to equations in (3.7) can be written as

$$\begin{aligned} Y &= FT^\dagger F^{(*)} + (I - EE^\dagger)^{(*)} W_1 (I - EE^\dagger), \\ Z &= L^{(*)} T^\dagger L + (I - K^\dagger K) W_2 (I - K^\dagger K)^{(*)}, \end{aligned}$$

where

$$F = C_1 M^\dagger A_1, E = M^\dagger B_1, K = A_1 M^\dagger, L = B_1 M^\dagger C_1.$$

Hence

$$\begin{aligned} &C_1 + C_1^{(*)} + Y + Z \\ &= (F + L^{(*)}) T^\dagger (F^{(*)} + L) + (I - EE^\dagger)^{(*)} W_1 (I - EE^\dagger) \\ &\quad + (I - K^\dagger K) W_2 (I - K^\dagger K)^{(*)} + C_1 - FT^\dagger L + C_1^{(*)} - L^{(*)} T^\dagger F^{(*)}. \end{aligned}$$

Recall (3.5), then

$$E^{(*)} (C_1 - FT^\dagger L) = B_1 (A_1 + B_1)^\dagger C_1 - TT^\dagger B_1 (A_1 + B_1)^\dagger C_1 = 0$$

and

$$(C_1 - FT^\dagger L) K^{(*)} = C_1 (A_1 + B_1)^\dagger A_1 - FT^\dagger T = 0.$$

Hence

$$\begin{aligned} C_1 + C_1^{(*)} + Y + Z &= (F + L^{(*)}) T^\dagger (F^{(*)} + L) \\ &\quad + \left[ (I - EE^\dagger)^{(*)} (I - K^\dagger K) \right] \\ &\quad \left[ \begin{array}{cc} W_1 & C_1 - FT^\dagger L \\ (C_1 - FT^\dagger L)^{(*)} & W_2 \end{array} \right] \left[ \begin{array}{c} I - EE^\dagger \\ (I - K^\dagger K)^{(*)} \end{array} \right] \end{aligned}$$

is G-positive if  $W_1$  and  $W_2$  are so chosen that

$$\left[ \begin{array}{cc} W_1 & C_1 - FT^\dagger L \\ (C_1 - FT^\dagger L)^{(*)} & W_2 \end{array} \right]$$

is G-positive. One such choice is  $W_1 = I$ ,

$W_2 = (C_1 - FT^\dagger L)^{(*)} (C_1 - FT^\dagger L)$ , in view of Theorem 2.1.

Let  $X_0$  be a G-positive solution of (1.1). Put  $Y = A_1 X_0 A_1$ ,  $Z = B_1 X_0 B_1$  and observe that  $Y, Z$  are G-positive solutions to equations (3.7), such that

$$N = C_1 + C_1^{(*)} + Y + Z = (A_1 + B_1) X_0 (A_1 + B_1)$$

is also G-positive. Then by Theorem 3.2,  $X_0$  can be expressed as (3.6).  $\square$

#### 4. G-repositive solution to some adjointable operator equations over Hilbert $C^*$ -modules

In order to get the G-repositive solution to some adjointable operator equations over the Hilbert  $C^*$ -modules, we need the following Lemma.

**Lemma 4.1.** *Let  $\mathcal{H}, \mathcal{K}$  be Hilbert  $C^*$ -modules. Assume that  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  and has closed range,  $C \in \mathfrak{B}(\mathcal{K})$ , then adjointable operator equation*

$$(4.1) \quad AX^{(*)} + XA^{(*)} = C,$$

*is consistent if and only if  $C$  is G-Hermitian and  $R_A C R_A^{(*)} = 0$ . In this case, the general solution of equation (4.1) can be expressed as*

$$(4.2) \quad X = \frac{1}{2} (I + R_A) \left( C (A^\dagger)^{(*)} - Y (A^\dagger A)^{(*)} \right) + Y - \frac{1}{2} A Y^{(*)} (A^\dagger)^{(*)},$$

where  $V \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  is arbitrary.

*Proof.* On the assumption that  $C$  is G-Hermitian and  $R_A C R_A^{(*)} = 0$ , it is easy to verify that  $X = \frac{(I+R_A)C(A^\dagger)^{(*)}}{2}$  satisfies equation (4.1). For the other direction, suppose that  $X_0$  satisfies the equation (4.1), then we have

$$C^{(*)} = \left( A X_0^{(*)} + X_0 A^{(*)} \right)^{(*)} = C$$

and

$$R_A C R_A^{(*)} = R_A \left( A X_0^{(*)} + X_0 A^{(*)} \right) R_A^{(*)} = 0.$$

Next we will prove that every solution of equation (4.1) can be expressed as (4.2). Suppose that  $X_0$  is an arbitrary solution of the equation (4.1), and setting  $Y = X_0$ , we have

$$X_0 = \frac{1}{2} (I + R_A) \left( C (A^\dagger)^{(*)} - X_0 (A^\dagger A)^{(*)} \right) + X_0 - \frac{1}{2} A X_0^{(*)} (A^\dagger)^{(*)}.$$

Then (4.2) is the general solution of equation (4.1).  $\square$

We can now prove the following result.

**Theorem 4.2.** *Let  $A, C \in \mathfrak{B}(\mathcal{H}_1, \mathcal{H}_2)$ ,  $A$  and  $CA^{(*)}$  have closed ranges. Then adjointable operator equation (3.1) has a  $G$ -repositive solution  $X \in \mathfrak{B}(\mathcal{H}_1)$  if and only if  $CA^{(*)}$  is  $G$ -repositive and  $\mathcal{R}(C) \subseteq \mathcal{R}(CA^{(*)})$ . In this case, the general  $G$ -repositive solution can be expressed as*

$$(4.3) \quad X = X_0 + \frac{1}{2}L_A \left( H - \left( X_0 + X_0^{(*)} \right) \right) \left( I + \left( A^\dagger A \right)^{(*)} \right) + \frac{1}{2}L_A Y L_A^* - \frac{1}{2}L_A Y^{(*)} L_A^{(*)}$$

with

$$H = X_2 + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)},$$

and

$$X_0 = A^\dagger C - \left( A^\dagger C \right)^{(*)} + A^\dagger A \left( A^\dagger C \right)^{(*)}, X_2 = A^\dagger \left( CA^{(*)} + AC^{(*)} \right) \left( A^\dagger \right)^{(*)},$$

$E, Y \in \mathfrak{B}(\mathcal{H}_1)$  and  $F \in \mathfrak{B}(\mathcal{H}_1)^{+}$  are arbitrary.

*Proof.* Suppose equation (3.1) has a  $G$ -repositive solution  $X$ , then  $AA^\dagger C = AA^\dagger AX = C$ . Further,  $CA^{(*)} + AC^{(*)} = A(X + X^{(*)})A^{(*)} \in \mathfrak{B}(\mathcal{H}_1)^{+}$ , implying that  $CA^{(*)}$  is  $G$ -repositive. Conversely, suppose  $AA^\dagger C = C$  and  $CA^{(*)}$  is  $G$ -repositive. Denote  $X_0 = A^\dagger C - \left( A^\dagger C \right)^{(*)} + A^\dagger A \left( A^\dagger C \right)^{(*)}$ , then  $AX_0 = C$  and

$$X_0 + X_0^{(*)} = A^\dagger \left( CA^{(*)} + AC^{(*)} \right) \left( A^\dagger \right)^{(*)} \in \mathfrak{B}(\mathcal{H}_1)^{+}.$$

Next we show that every  $G$ -repositive solution to equation (3.1) can be written as (4.4). It is well known that the general solution of equation (3.1) can be expressed as

$$(4.4) \quad X = X_0 + L_A W,$$

where  $W$  is free to vary over  $\mathfrak{B}(\mathcal{K}_2, \mathcal{H})$ . Denote

$$X + X^{(*)} = X_0 + X_0^{(*)} + L_A W + (L_A W)^{(*)} = H$$

then

$$X + X^{(*)} \in \mathfrak{B}(\mathcal{H}_1)^{+} \Leftrightarrow H \in \mathfrak{B}(\mathcal{H}_1)^{+}.$$

If you fix  $H$ , it is easy to get  $H = H^{(*)}$ , from Lemma 4.1, equation

$$L_A W + (L_A W)^{(*)} = H - \left( X_0 + X_0^{(*)} \right)$$

is consistent for  $W$  if and only if

$$R_{L_A} C R_{L_A}^{(*)} = A^\dagger A \left( H - \left( X_0 + X_0^{(*)} \right) \right) \left( A^\dagger A \right)^{(*)} = 0,$$

which is equivalent to equation

$$(4.5) \quad A^\dagger A H \left( A^\dagger A \right)^{(*)} = A^\dagger A \left( X_0 + X_0^{(*)} \right) \left( A^\dagger A \right)^{(*)}$$

has a G-positive solution  $H$ . Recall that  $CA^{(*)}$  is G-repositive, thus

$$\begin{aligned} & A^\dagger A \left( X_0 + X_0^{(*)} \right) \left( A^\dagger A \right)^{(*)} \\ &= A^\dagger A \left( A^\dagger \left( CA^{(*)} + AC^{(*)} \right) \left( A^\dagger \right)^{(*)} \right) \left( A^\dagger A \right)^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}. \end{aligned}$$

It follows from Theorem 3.2 that equation (4.5) has a G-positive solution which can be expressed as

$$(4.6) \quad \begin{aligned} H &= X_2 + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} \\ &\quad + L_A F L_A^{(*)}, \end{aligned}$$

where  $X_2 = A^\dagger \left( CA^{(*)} + AC^{(*)} \right) \left( A^\dagger \right)^{(*)}$ ,  $E \in \mathfrak{B}(\mathcal{H})$  and  $F \in \mathfrak{B}(\mathcal{H})^{(+)}$  are arbitrary. Combining Lemma 4.1, we have

$$(4.7) \quad \begin{aligned} W &= \frac{1}{2} \left( L_A H - L_A \left( X_0 + X_0^{(*)} \right) - L_A Y \right) \left( I + \left( A^\dagger A \right)^{(*)} \right) \\ &\quad + Y - \frac{1}{2} L_A Y^{(*)} L_A^{(*)}, \end{aligned}$$

where  $Y$  is arbitrary. Further, the G-repositive solution of equation (3.1) can be expressed as (4.4) after taking (4.8) into (4.4).  $\square$

The following Lemma plays an important role to get the G-repositive solution of equation (3.3).

**Lemma 4.3.** *Let  $\mathcal{H}, \mathcal{K}$  be Hilbert  $C^*$ -modules. Assume that  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  and has closed range. Then the general G-skew-Hermitian solution of*

$$(4.8) \quad A X A^{(*)} = 0$$

can be expressed as

$$(4.9) \quad X = L_A W - W^{(*)} L_A^{(*)},$$

where  $W \in \mathfrak{B}(\mathcal{K})$  is arbitrary.

*Proof.* Obviously,  $X$  defined by (4.9) is G-skew-Hermitian and satisfies equation (4.8). Suppose  $X_0$  is a G-skew-Hermitian solution to (4.8), setting  $W = \frac{1}{2}X_0(I + A^\dagger A)$ , then

$$X_0 = \frac{1}{2}L_A X_0 (I + A^\dagger A) - \frac{1}{2} \left( X_0 (I + A^\dagger A) \right)^{(*)} L_A^{(*)}.$$

Thus (4.9) is the general G-skew-Hermitian solution to equation (4.8).  $\square$

We can now prove the following result.

**Theorem 4.4.** *Let  $\mathcal{H}, \mathcal{K}$  be Hilbert  $C^*$ -modules. Assume that  $A \in \mathfrak{B}(\mathcal{H}, \mathcal{K})$  and has closed range,  $C \in \mathfrak{B}(\mathcal{K})$  is G-Hermitian and  $\mathcal{R}(C) \subseteq \mathcal{R}(A)$ . Then equation (3.3) has a G-repositive solution  $X \in \mathfrak{B}(\mathcal{H})$  if and only if  $C$  is G-repositive. If, in addition,  $C$  has closed range, the general G-repositive solution of (3.3) can be expressed as*

$$(4.10) X = X_2 + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} \\ + L_A F L_A^{(*)} + L_A W - W^{(*)} L_A^{(*)}$$

with  $X_2 = A^\dagger C (A^\dagger)^{(*)}$  is a particular G-repositive solution,  $E, W \in \mathfrak{B}(\mathcal{H})$  and  $F \in \mathfrak{B}(\mathcal{H})^{(+)}$  are arbitrary.

*Proof.* Denote  $H_p(X) = \frac{1}{2}(X + X^{(*)})$ . If  $X$  is a G-repositive solution to equation (3.3), then  $H_p(C) = A H_p(X) A^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}$ . For the other direction, if  $C$  is G-repositive then  $X_2 = A^\dagger C (A^\dagger)^{(*)}$  is a G-repositive solution to equation (3.3). Next we will show every G-repositive solution of (3.3) can be expressed as (4.11). If  $X$  is an arbitrary G-repositive solution to equation (3.3), then  $H_p(X)$  is a G-positive solution to

$$(4.11) \quad A H_p(X) A^{(*)} = H_p(C).$$

It follows from Theorem 3.2 that

$$H_p(X) = X_2 + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)}$$



where  $X_2 = A^\dagger H_p(C) (A^\dagger)^{(*)}$  is a particular G-positive solution to equation (4.11),  $E \in \mathfrak{B}(\mathcal{H})$  and  $F \in \mathfrak{B}(\mathcal{H})^{(+)}$  are arbitrary. Note that

$$\begin{aligned} H_p(X) &= H_p \left( A^\dagger C \left( A^\dagger \right)^{(*)} + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} \right. \\ &\quad \left. + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)} \right) \end{aligned}$$

implies that

$$\begin{aligned} X &= A^\dagger C \left( A^\dagger \right)^{(*)} + X_2 X_2^\dagger E L_A^{(*)} + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} \\ &\quad + L_A F L_A^{(*)} + Z \end{aligned}$$

where  $H_p(Z) = 0$  and  $AZA^{(*)} = 0$ . By the use of Lemma 4.3, we have

$$Z = L_A W - W^{(*)} L_A^{(*)},$$

where  $W \in \mathfrak{B}(\mathcal{H})$  is arbitrary. Hence, (4.11) is the general G-repositive solution to equation (3.3).  $\square$

**Theorem 4.5.** *Let  $\mathcal{H}_i (i = 1, 2, \dots, 4)$  be Hilbert  $C^*$ -modules,  $A \in \mathfrak{B}(\mathcal{H}_1, \mathcal{H}_2)$ ,  $B \in \mathfrak{B}(\mathcal{H}_3, \mathcal{H}_1)$ ,  $C \in \mathfrak{B}(\mathcal{H}_3, \mathcal{H}_2)$ . Denote*

$$\begin{aligned} A_1 &= A^{(*)} V^{-1} A, B_1 \\ &= B V B^{(*)}, C_1 \\ &= A^{(*)} C B^{(*)}, M \\ &= A_1 + B_1, T \\ &= B_1 M^\dagger C_1 M^\dagger A_1, \end{aligned}$$

and

$$H(X) = X + X^{(*)}.$$

*Suppose that  $A, B, T$  and  $M$  have closed ranges. Then consistent equation (1.1) has a G-repositive solution if and only if  $T$  is G-repositive. In this case, the general G-repositive solution of equation (1.1) can be expressed as*

(4.12)

$$\begin{aligned} X &= M^\dagger (C_1 + Y + Z + W) M^\dagger + X_2 + X_2 X_2^\dagger E L_A^{(*)} \\ &\quad + L_A E^{(*)} \left( X_2 X_2^\dagger \right)^{(*)} + L_A E^{(*)} X_2^\dagger E L_A^{(*)} + L_A F L_A^{(*)} + L_A W - W^{(*)} L_A^{(*)}, \end{aligned}$$

where  $Y, Z$  and  $W$  are arbitrary solutions of

$$(4.13) \quad YM^\dagger B_1 = C_1M^\dagger A_1, \quad A_1M^\dagger Z = B_1M^\dagger C_1, \quad AM^\dagger WM^\dagger B = T$$

such that  $C_1+Y+Z+W$  is  $G$ -repositive,  $X_2 = M^\dagger (C_1 + Y + Z + W) M^\dagger$ ,  $E, W \in \mathfrak{B}(\mathcal{H}_1)$  and  $F \in \mathfrak{B}(\mathcal{H}_1)^{(+)}$  are arbitrary.

*Proof.* Since  $\mathcal{R}(B_1) \subseteq \mathcal{R}(M)$ , then  $M^\dagger B_1 B_1^\dagger M M^\dagger B_1 = M^\dagger B_1$ , which gives that  $M^\dagger B_1$  is regular. Note that

$$\begin{aligned} C_1M^\dagger A_1 \left(M^\dagger B_1\right)^- M^\dagger B_1 &= C_1M^\dagger A_1 B_1^\dagger M M^\dagger B_1 \\ &= C_1M^\dagger A_1 B_1^\dagger B_1 \\ &= C_1 B_1^\dagger B_1 M^\dagger A_1 B_1^\dagger B_1 \\ &= C_1 B_1^\dagger A_1 M^\dagger B_1 \\ &= C_1M^\dagger A_1, \end{aligned}$$

then equation  $YM^\dagger B_1 = C_1M^\dagger A_1$  is consistent. Similarly, we can get the other equations in (4.13) are consistent. Now suppose that equation (1.1) has a  $G$ -repositive solution  $X$ , then

$$\begin{aligned} H(T) &= H\left(B_1M^\dagger C_1M^\dagger A_1\right) = H\left(B_1M^\dagger A_1 X B_1M^\dagger A_1\right) \\ &= B_1M^\dagger A_1 H(X) \left(B_1M^\dagger A_1\right)^{(*)} \in \mathfrak{B}(\mathcal{H})^{(+)}. \end{aligned}$$

For the other direction, suppose  $T$  is  $G$ -repositive. Since

$$\begin{aligned} &A_1M^\dagger (C_1 + Y + Z + W) M^\dagger B_1 \\ &= A_1M^\dagger C_1M^\dagger B_1 + A_1M^\dagger Y M^\dagger B_1 + A_1M^\dagger Z M^\dagger B_1 + A_1M^\dagger W M^\dagger B_1 \\ &= A_1M^\dagger C_1M^\dagger B_1 + A_1M^\dagger C_1M^\dagger A_1 + B_1M^\dagger C_1M^\dagger B_1 + B_1M^\dagger C_1M^\dagger A_1 \\ &= (A_1 + B_1) M^\dagger C_1 M^\dagger (A_1 + B_1) = C_1, \end{aligned}$$

thus

$$X_0 = M^\dagger (C_1 + Y + Z + W) \left(M^\dagger\right)^{(*)}$$

satisfies equation (1.1), where  $Y, Z$  and  $W$  are solutions of equations in (4.13). Next, we only need to prove that for some proper choices of  $Y, Z$  and  $W$ ,  $C_1 + Y + Z + W$  is  $G$ -repositive, which is equivalent to  $X_0$  is  $G$ -repositive. Setting

$$M^\dagger B_1 = E, F = C_1M^\dagger A_1, K = A_1M^\dagger, L = B_1M^\dagger C_1,$$

and choose some special solutions of equations in (4.13),

$$\begin{aligned} Y &= FE^\dagger - (FE^\dagger)^{(*)} + (E^\dagger)^{(*)} F^{(*)} EE^\dagger + R_E^{(*)} R_E, \\ Z &= K^\dagger L - (K^\dagger L)^{(*)} + K^\dagger K (K^\dagger L)^{(*)} + L_K Q L_K^{(*)}, \\ W &= K^\dagger T E^\dagger - L_K S - S R_E, \end{aligned}$$

where

$$Q = (C_1^{(*)} - K^\dagger T^{(*)} E^\dagger) (C_1^{(*)} - K^\dagger T^{(*)} E^\dagger)^{(*)}, S = K^\dagger K C^{(*)} + C^{(*)} E E^\dagger.$$

Obviously,

$$\begin{aligned} H(Y) &= (E^\dagger)^{(*)} G(T) E E^\dagger + R_E^{(*)} R_E, \\ H(Z) &= K^\dagger G(T) (K^\dagger)^{(*)} + L_K G(Q) L_K^{(*)}, \\ H(W) &= K^\dagger T E^\dagger + (K^\dagger T E^\dagger)^{(*)} - G(C_1^{(*)} E E^\dagger + K^\dagger K C_1^{(*)} - 2K^\dagger T^{(*)} E^\dagger). \end{aligned}$$

Noting that

$$\begin{aligned} K^\dagger K K^\dagger T^{(*)} E^\dagger &= K^\dagger K L^{(*)} E^\dagger = K^\dagger T^{(*)} E^\dagger, \\ K^\dagger T^{(*)} E^\dagger E E^\dagger &= K^\dagger F^{(*)} E E^\dagger = K^\dagger T^{(*)} E^\dagger, \\ K C^{(*)} E &= K L^{(*)} = T^{(*)}, \end{aligned}$$

we have

$$\begin{aligned} &H(C_1 + Y + Z + W) \\ &= \left( (E^\dagger)^{(*)} + K^\dagger \right) H(T) \left( (E^\dagger)^{(*)} + K^\dagger \right)^{(*)} \\ &+ \begin{bmatrix} (I - E E^\dagger)^{(*)} & (I - K^\dagger K) \end{bmatrix} D \begin{bmatrix} I - E E^\dagger \\ (I - K^\dagger K)^{(*)} \end{bmatrix} \end{aligned}$$

where

$$D = \begin{bmatrix} I & C_1 - (E^\dagger)^{(*)} T^\dagger (K^\dagger)^{(*)} \\ (C_1 - (E^\dagger)^{(*)} T^\dagger (K^\dagger)^{(*)})^{(*)} & H(Q) \end{bmatrix}.$$

It follows from Theorem 2.1, that  $D$  is G-positive, then  $X_0$  is G-repositive. Hence, with such a choice of  $Y, Z$  and  $W$ , it can be seen the  $X_0$  is a G-repositive solution to equation (3.6). Next we only need to prove that

every  $G$ -repositive solution of (1.1) can be written as form (4.12). Suppose  $X$  is an arbitrary  $G$ -repositive solution of equation (1.1). It is easy to verify that  $Y = AXA, Z = BXB, W = BXA$  are solutions of equations in (4.13), and

$$(A + B)X(A + B) = C + Y + Z + W,$$

is  $G$ -repositive. Then it follows by Theorem 4.4 that  $X$  can be expressed as (4.12).  $\square$

## 5. Conclusion

In this paper, we have presented a criterion for an adjointable operator to be  $G$ -positive ( $G$ -repositive), and derived some necessary and sufficient conditions for the existence of a  $G$ -positive ( $G$ -repositive) solution to adjointable operator equations  $AX = C, AXA^{(*)} = C$  and  $AXB = C$  over Hilbert  $C^*$ -modules, respectively. Moreover, we have shown the expressions of the general  $G$ -positive and  $G$ -repositive solutions to these equations when the solvability conditions are satisfied.

Motivated by the results in the paper, and observing that equations (3.1), (3.3) and (1.1) are all special cases of the system of adjointable operator equations

$$(5.1) \quad A_1X = C_1, XB_2 = C_2, A_3XB_3 = C_3$$

over Hilbert  $C^*$ -modules, it would be of interest to investigate the  $G$ -positive solutions to system (5.1). We will show the results in a forthcoming paper.

## Acknowledgments

The author is very much indebted to the anonymous referees for their constructive and valuable comments and suggestions which greatly improve the original version of this paper.

## REFERENCES

- [1] M. L. Arias and M. C. Gonzalez, Positive solutions to operator equations  $AXB = C$ , *Linear Algebra Appl.* **433** (2010), no. 6, 1194–1202.
- [2] J. K. Baksalary, Nonnegative definite and positive definite solutions to the matrix equation  $AXA^* = B$ , *Linear Mult. Algebra* **16** (1984), no. 1-4, 133–139.
- [3] D. S. Cvetković-Ilić, A. Dajić and J. J. Koliha, Positive and real-positive solutions to the equation  $axa^* = c$  in  $C^*$ -algebras, *Linear Mult. Algebra* **55** (2007), no. 6, 535–543.

- [4] A. Dajić and J. J. Koliha, Equations  $ax = c$  and  $xb = d$  in rings and rings with involution with applications to Hilbert space operators, *Linear Algebra Appl.* **429** (2008), no. 7, 1779–1809.
- [5] A. Dajić and J. J. Koliha, Positive solutions to the equations  $AX = C$  and  $XB = D$  for Hilbert space operators, *J. Math. Anal. Appl.* **333** (2007), no. 2, 567–576.
- [6] J. Dieudonné, QuasihHermitian Operators, 115–122, Proceedings of International Symposium on Linear Spaces, Jerusalem, 1961.
- [7] C. Dong, Q. Wang and Y. Zhang, The common positive solution to adjointable operators equations with an application, *J. Math. Anal. Appl.* **396** (2012), no. 2, 670–679.
- [8] F. Farid, M. S. Moslehian, Q. Wang and Z. Wu, On the Hermitian solutions to a system of adjointable operator equations, *Linear Algebra Appl.* **437** (2012), no. 7, 1854–1891.
- [9] J. Groß, Explicit solutions to the matrix inverse problem  $AX = B$ , *Linear Algebra Appl.* **289** (1999), no. 1-3, 131–134.
- [10] C. Jiang, On products of two hermitian operators, *Linear Algebra Appl.* **430** (2009), no. 1, 553–557.
- [11] I. Kaplansky, Modules over operator algebras, *Amer. J. Math.* **75** (1953) 839–858.
- [12] C. G. Khatri and S. K. Mitra, Hermitian and nonnegative definite solutions of linear matrix equations, *SIAM J. Appl. Math.* **31** (1976), no. 4, 579–585.
- [13] E. C. Lance, Hilbert  $C^*$ -Modules, A Toolkit for Operator Algebraists, Cambridge University Press, Cambridge, 1995.
- [14] H. Radjavi and J. P. Williams, Products of self-adjoint operators, *Michigan Math. J.* **16** (1969) 177–185.
- [15] S. Sun and X. Ma, Generalized hermitian operators, *Linear Algebra Appl.* **433** (2010), no. 4, 737–749.
- [16] Q. Wang and C. Dong, Positive solutions to a system of adjointable operator equations over the Hilbert  $C^*$ -modules, *Linear Algebra Appl.* **433** (2010), no. 7, 1481–1489.
- [17] Q. Wang and C. Dong, The general solution to a system of adjointable operator equations over the Hilbert  $C^*$ -modules, *Oper. Matrices* **5** (2011), no. 2, 333–350.
- [18] Q. Wang and Z. Wu, Common Hermitian solutions to some operator equations on Hilbert  $C^*$ -modules, *Linear Algebra Appl.* **432** (2010), no. 12, 3159–3171.
- [19] Q. Wang and F. Zhang, The reflexive re-nonnegative definite solution to a quaternion matrix equation, *Electron. J. Linear Algebra* **17** (2008) 88–101.
- [20] Q. Wang and C. Yang, The Re-nonnegative definite solutions of the matrix equation  $AXB = C$ , *Comment. Math. Univ. Carolin.* **39** (1998), no. 1, 7–13.
- [21] N. E. Wegge-Olsen,  $K$ -Theory and  $C^*$ -Algebras, A Friendly Approach, Oxford University Press, Oxford, England, 1993.
- [22] Q. Xu, Common hermitian and positive solutions to the adjointable operator equations  $AX = C$ ,  $XB = D$ , *Linear Algebra Appl.* **429** (2008), no. 1, 1–11.
- [23] Q. Xu, L. Sheng and Y. Gu, The solutions to some operator equations, *Linear Algebra Appl.* **429** (2008), no. 8-9, 1997–2024.

- [24] X. Zhang, Hermitian nonnegative-definite and positive-definite solutions of the matrix equation  $AXB = C$ , *Appl. Math. E-Notes* **4** (2004) 40–47.

**Guangjing Song**

School of Mathematics and Information Sciences, University of Weifang, P.O. Box 261061, WeiFang, P. R. China

Email: [sgjshu@163.com](mailto:sgjshu@163.com)